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BAYESIAN NETWORKS MEET OBSERVATIONAL DATA

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Credit Card Fraud Detection Using Bayesian and Neural Networks

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Abstract

This paper discusses automated credit card fraud detection by means of machine learning. In an era of digitalization, credit card fraud detection is of great importance to financial institutions. We apply two machine learning techniques suited for reasoning under uncertainty: artificial neural networks and

do the fraud detection. After a process of learning, the program is supposed to be able to correctly classify a transaction it has never seen before as fraudulent or not fraudulent, given some features of that transaction.

The structure of this paper is as follows: first we introduce the reader to the domain of credit card fraud detection. In Sections 3 and 4 we briefly ex-

Credit Card Fraud Detection
Using Bayesian and Neural Networks

Sam Maes Karl Tuyls Bram Vanschoenwinkel

experiment	$\pm 10\%$ false pos	$\pm 15\%$ false pos
ANN-fig 2(a)	60% true pos	70% true pos
ANN-fig 2(a)	47% true pos	58% true pos
ANN-fig 2(c)	60% true pos	70% true pos
BBN-fig 2(c)	68% true pos	74% true pos
BBN-fig 2(g)	68% true pos	74% true pos

Abstract

This paper discusses credit card fraud detection by means of machine learning. With the advent of digitalization, credit card fraud has gained great importance to financial institutions. We compare two machine learning techniques suited for reasoning under uncertainty: artificial neural networks and

Table 1: This table compares the results achieved with ANN and BBN, for a false positive rate of respectively 10% and 15%.

process of learning, we aim to correctly classify transactions before as fraudulent. The features of that process are as follows: first we introduce the reader to the domain of credit card fraud detection. In Sections 3 and 4 we briefly ex-

MOTIVATIONAL EXAMPLE: VETERINARY EPIDEMIOLOGY DATA VISUALISATION



Contents lists available at [SciVerse ScienceDirect](https://www.sciencedirect.com)

Preventive Veterinary Medicine

journal homepage: www.elsevier.com/locate/prevetmed



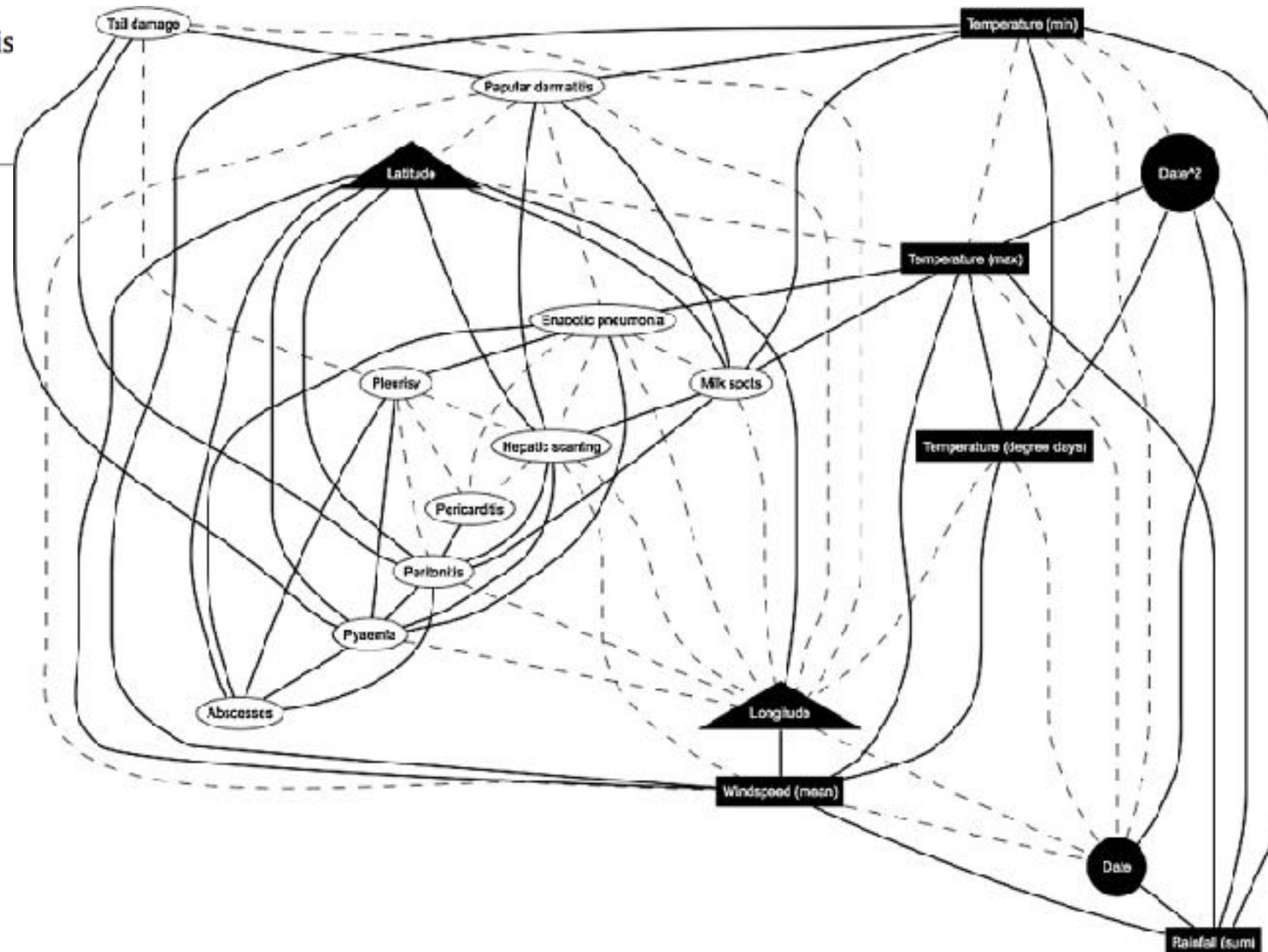
Using Bayesian networks to explore the role of weather as a potential determinant of disease in pigs

B.J.J. McCormick^a, M.J. Sanchez-Vazquez^b, F.I. Lewis

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MOTIVATIONAL EXAMPLE: SOCIAL SCIENCES DATA INTERPRETATION

Discovering complex interrelationships between socioeconomic status and health in Europe: A case study applying Bayesian Networks

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^b Complutense University of Madrid, Department of Sociology IV (Research Methodology and Communication Theory), Campus de Somosaguas, Faculty of Political

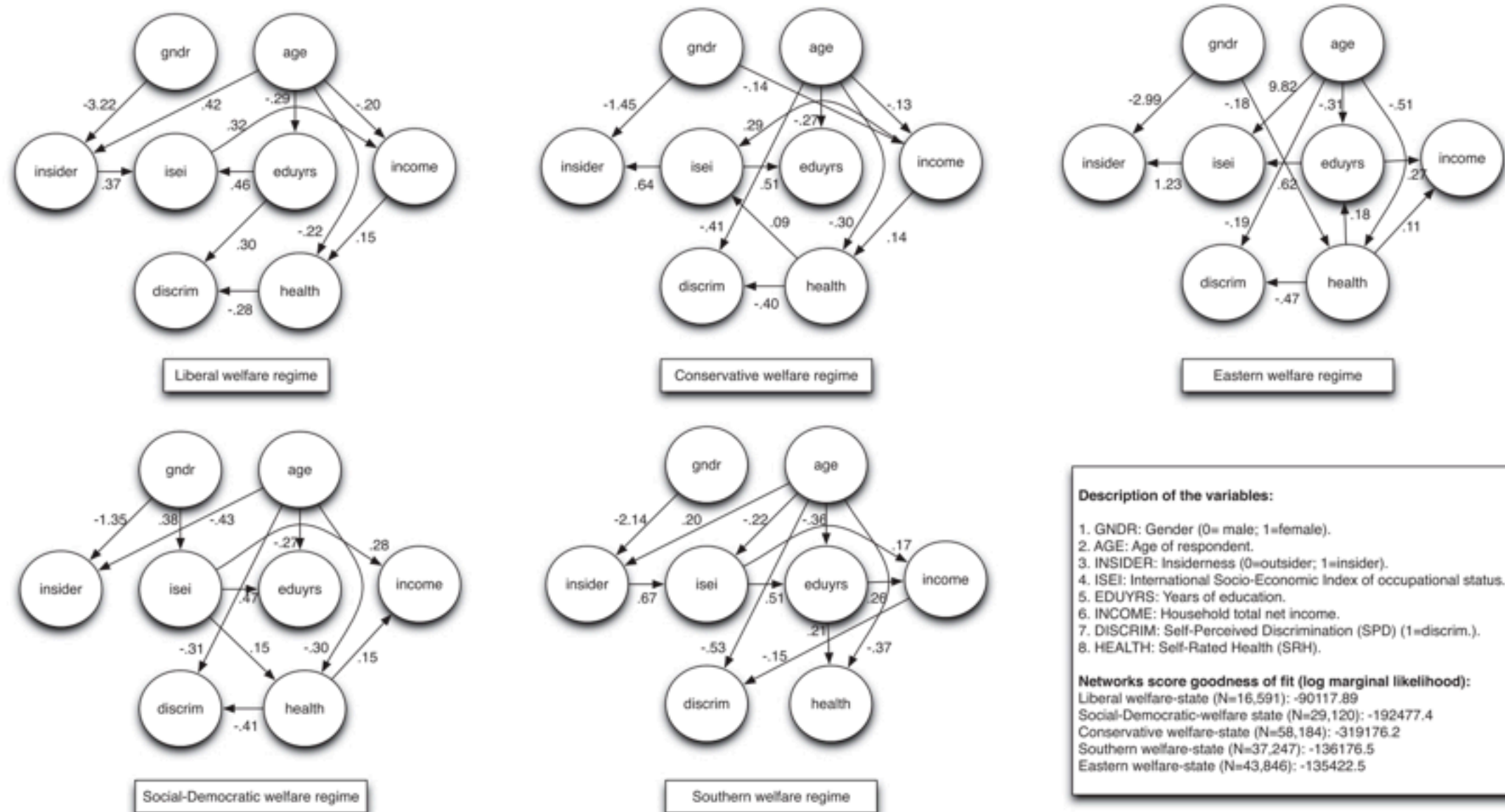


Fig. 1. Bayesian networks describing interrelationships between SES and health in five European welfare states.

BAYESIAN NETWORKS IN THE MACHINE LEARNING WORLD

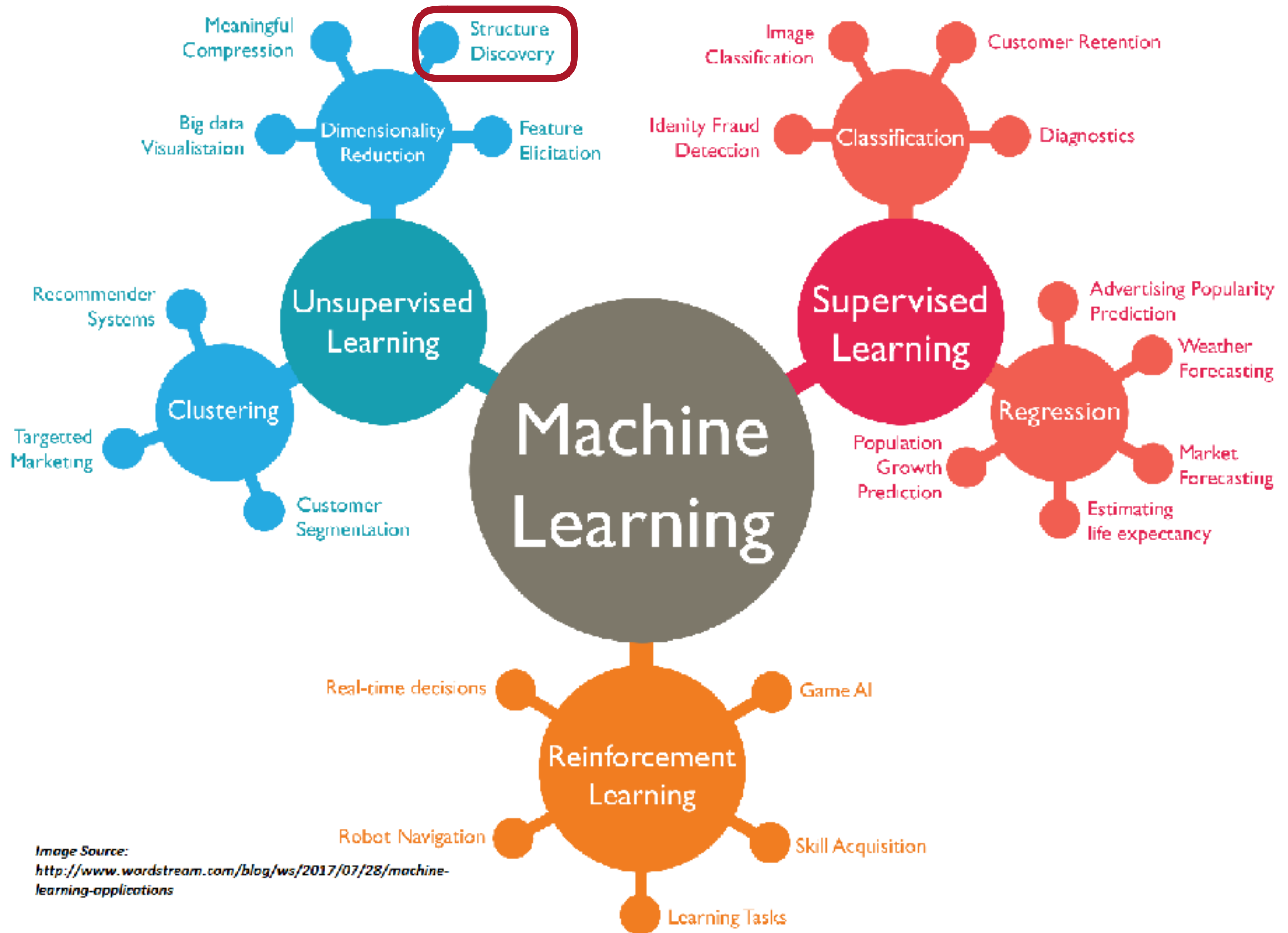


Image Source:
<http://www.wordstream.com/blog/ws/2017/07/28/machine-learning-applications>

OUTLINE OF THE TALK

Objectif of the talk:

How to **learn Bayesian networks** from observational data?

OUTLINE OF THE TALK

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select

How to ~~learn~~ Bayesian networks from observational data?

Bayesian Networks are defined by two elements:

Network structure:

Directed Acyclic Graph (**DAG**): $G = (V, A)$

in which each node $v_i \in V$ corresponds to a random variable X_i

Probability distribution:

Probability distribution X with parameters Θ , which can be factorised into smaller local probability distributions according to the arcs $a_{ij} \in A$ present in the graph.

A BN encodes the factorisation of the joint distribution

$$P(\mathbf{X}) = \prod_{j=1}^n P(X_j \mid \mathbf{Pa}_j, \Theta_j), \text{ where } \mathbf{Pa}_j \text{ is the set of parents of } X_j$$

OUTLINE OF THE TALK

Objectif of the talk:

~~How to learn Bayesian networks from observational data?~~

Which approaches do exist?

Which assumptions/limitations are involved when learning a Bayesian network from observational dataset?

Theoretical limitations:

- ▶ BN learning is **ill-posed on two levels**
 - ▶ Finite sample (any stats problem is ill-posed)
 - ▶ Complete knowledge of observational distribution usually does not determine the underlying causal model

OUTLINE OF THE TALK

Objectif of the talk:

~~How to learn Bayesian networks from observational data?~~

Which approaches do exist?

Which assumptions/limitations are involved when learning a Bayesian network from observational dataset?

Technical limitations:

- ▶ Approximate learning process
- ▶ Proxies
- ▶ Combinatorial wall!!!
 - ▶ Simplification needed

COMBINATORIAL WALL

# Nodes	# DAGs	Inference	Typical domain of interest
1 - 15 Nodes	$< 10^{41}$ DAGs	Exact inference	<div>EPIDEMIOLOGY</div> <div>GENOMICS</div> <div>PROTEOMICS</div>
16 - 25 Nodes	$< 10^{100}$ DAGs	Exact inference possible	
26 - 50 Nodes	$< 10^{400}$ DAGs	Approximate inference	
51 - 100 Nodes	$< 10^{1700}$ DAGs	Approximate inference	
101 - 1000 Nodes	$< 10^{100000}$ DAGs	(very) approximative inference	

Approximations:

- ▶ limiting number of parents per node
- ▶ Decomposable scores/efficient algorithm
- ▶ Score equivalence

PLAN

1. From observationnal dataset deduce probabilistic model
 - Usually discrete BN or jointly Gaussian
 - Epidemiological constrain: mixture of distributions
2. From probabilistic model deduce structure

EXPONENTIAL FAMILY

Observational dataset

X1	X2	X3	...
12	23	53	...
32	31	23	...
10	16	45	...
...



Probabilistic model

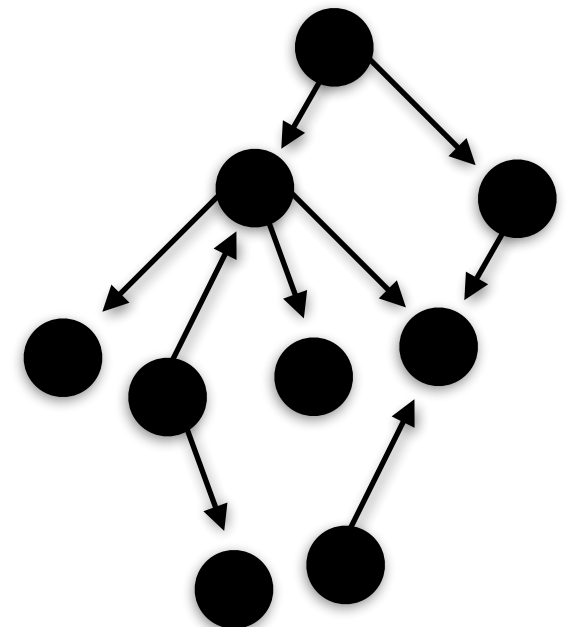
$$P(X_1, \dots, X_n) = P(X_i | X_j, \dots) \dots$$

Independance
testing

Computing directly



Network structure



SOME ELEMENTS OF PROBABILITY THEORY

The **conditional probability** of A given B is: $P(A \mid B) = \frac{P(A, B)}{P(B)}$

Bayes theorem: $P(A \mid B) = \frac{P(B \mid A)P(A)}{P(B)}$

Let A, B and C non intersecting subsets of nodes in a DAG G

A is **conditionally independent** of B given C if: $A \perp\!\!\!\perp_P B \mid C$

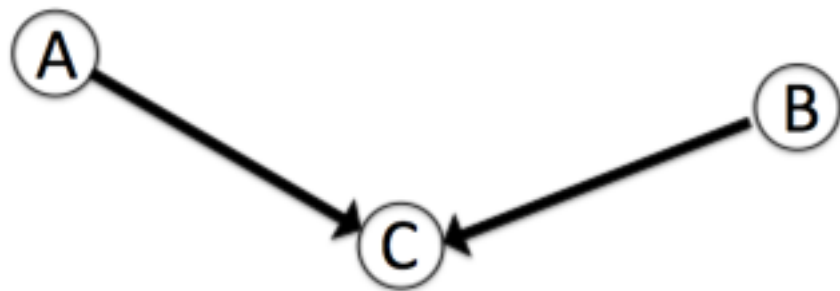
$$P(A, B \mid C) = P(A \mid C)P(B \mid C)$$

Let A , B and C non intersecting subsets of nodes in a DAG G

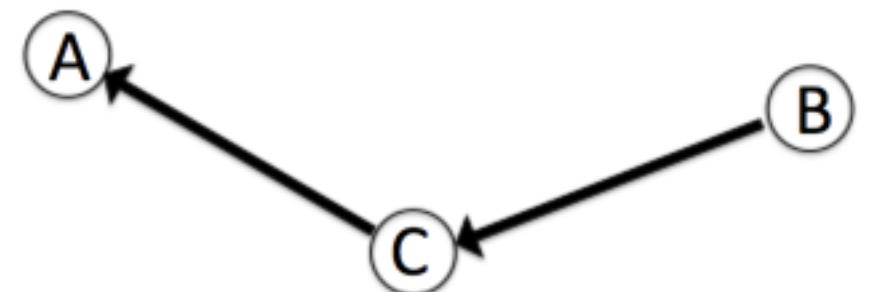
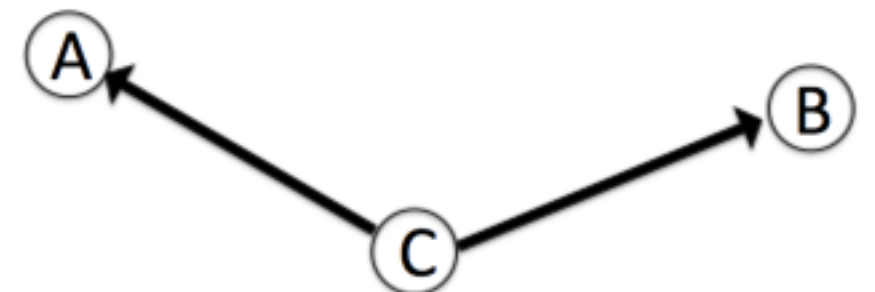
A is **conditionally independent** of B given C if: $A \perp_P B | C$

$$P(A, B | C) = P(A | C)P(B | C)$$

$$A \not\perp_P B | C$$

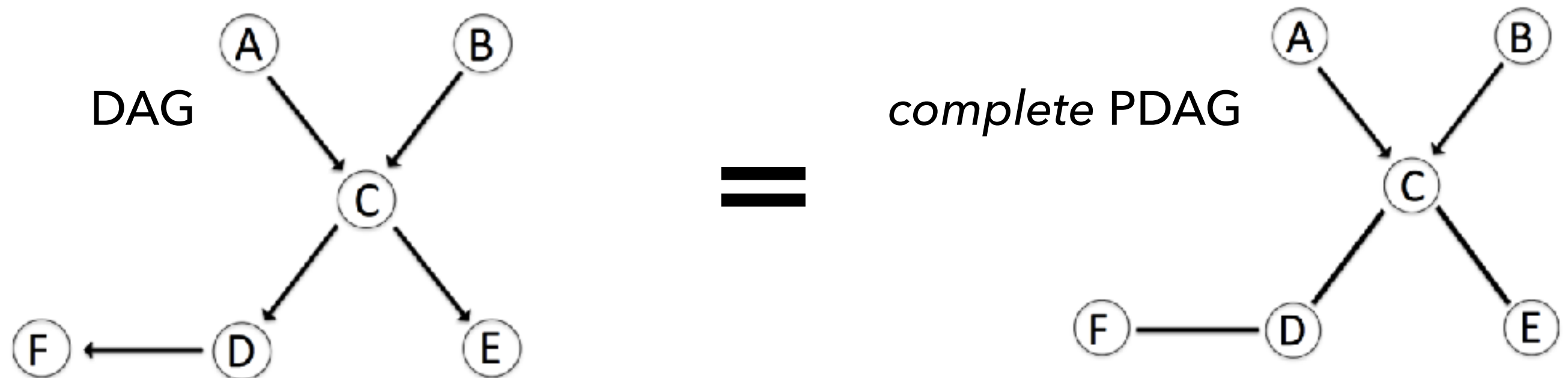


$$A \perp_P B | C$$



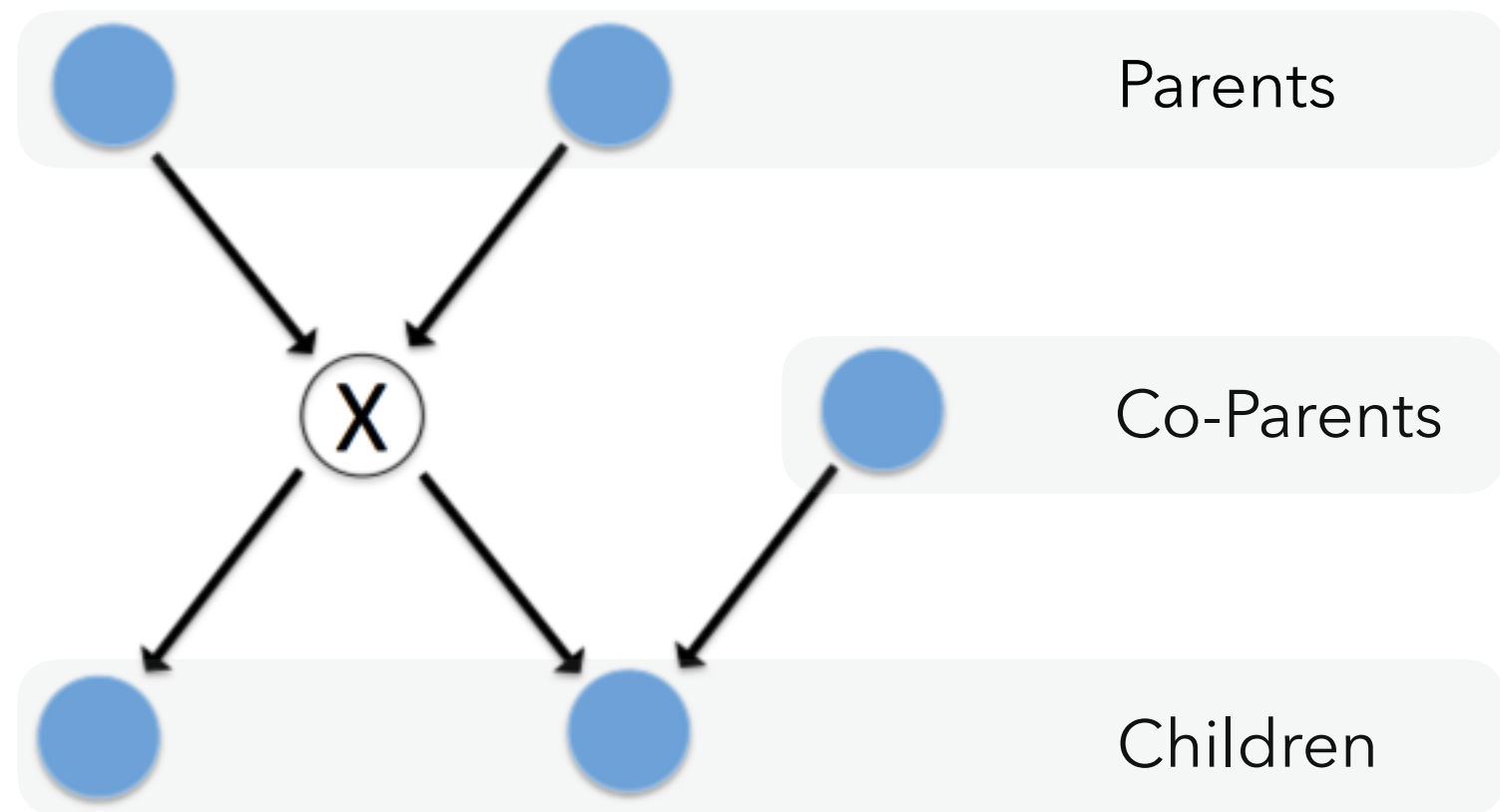
LEARNING BAYESIAN NETWORKS

- ▶ In a practical perspective, for **observational** data, if learning algorithms rely on **probabilistic learning algorithm**. Then one can learn up to the **Markov equivalence class**.
- ▶ **Markov equivalence class** are the set of DAGs that have the same **skeleton** and **v-structure**.



ELEMENT OF GRAPH THEORY: MARKOV BLANKET

The **Markov Blanket** of a node is the set of **parents**, **co-parents** and **children**.



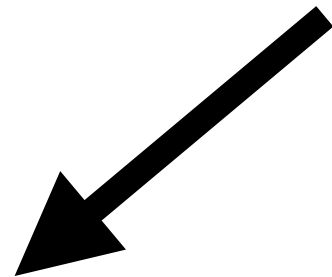
$$P(X_k \mid X_n, k \neq n) = P(X_k \mid X_{\text{MB}(k)}), \forall k$$

The **Markov Blanket** of a node is the set of nodes that **shields** the index node from the rest of the network

Local Markov property:

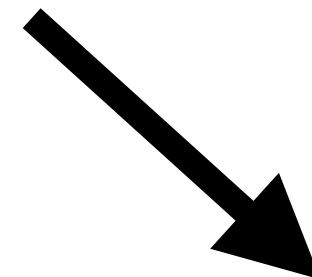
$$X \perp \text{Non-Descendants}(X) \mid Pa(X)$$

$$\mathcal{M} = (\mathcal{S}, \Theta_{\mathcal{M}})$$



Model selection

Structure learning



Parameter estimation

Parameter learning

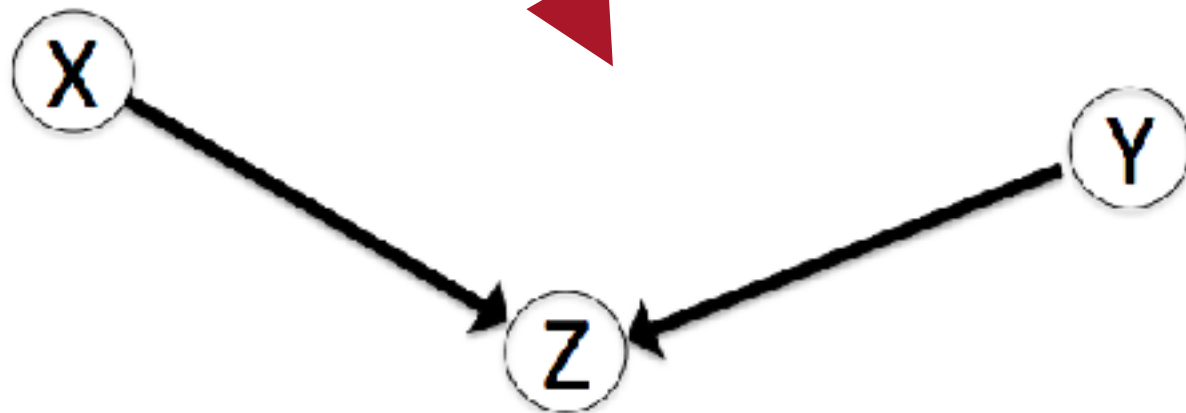
$$P(\mathcal{M}|\mathcal{D}) = \underbrace{P(\Theta_{\mathcal{M}}, \mathcal{S}|\mathcal{D})}_{\text{model learning}} = \underbrace{P(\Theta_{\mathcal{M}}|\mathcal{S}, \mathcal{D})}_{\text{parameter learning}} \cdot \underbrace{P(\mathcal{S}|\mathcal{D})}_{\text{structure learning}}$$

Constraint based algorithms

$$P_{X \perp\!\!\!\perp Y|Z} < \alpha$$



$$X \perp_{\mathcal{S}} Y|Z = X \perp Y|Z$$



Search-and-score algorithms

Maximum a posteriori score

$$G^* = \operatorname{argmax}_G f(\mathcal{D}, G, n, \dots)$$

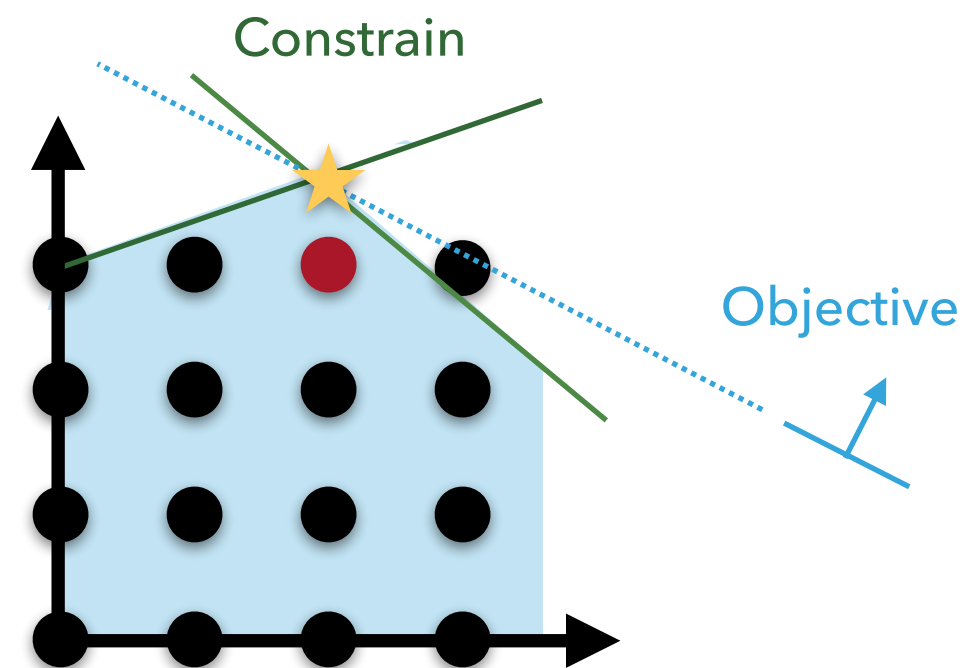
Example of scoring functions:

- ▶ Bayesian or ML scores
 - ▶ Bayesian Posterior
 - ▶ Bayesian-Dirichlet (BDeu, BDs, BDe)
 - ▶ Bayesian Information Criterion (BIC)

LEARNING BAYESIAN NETWORKS

Score-and-search algorithms

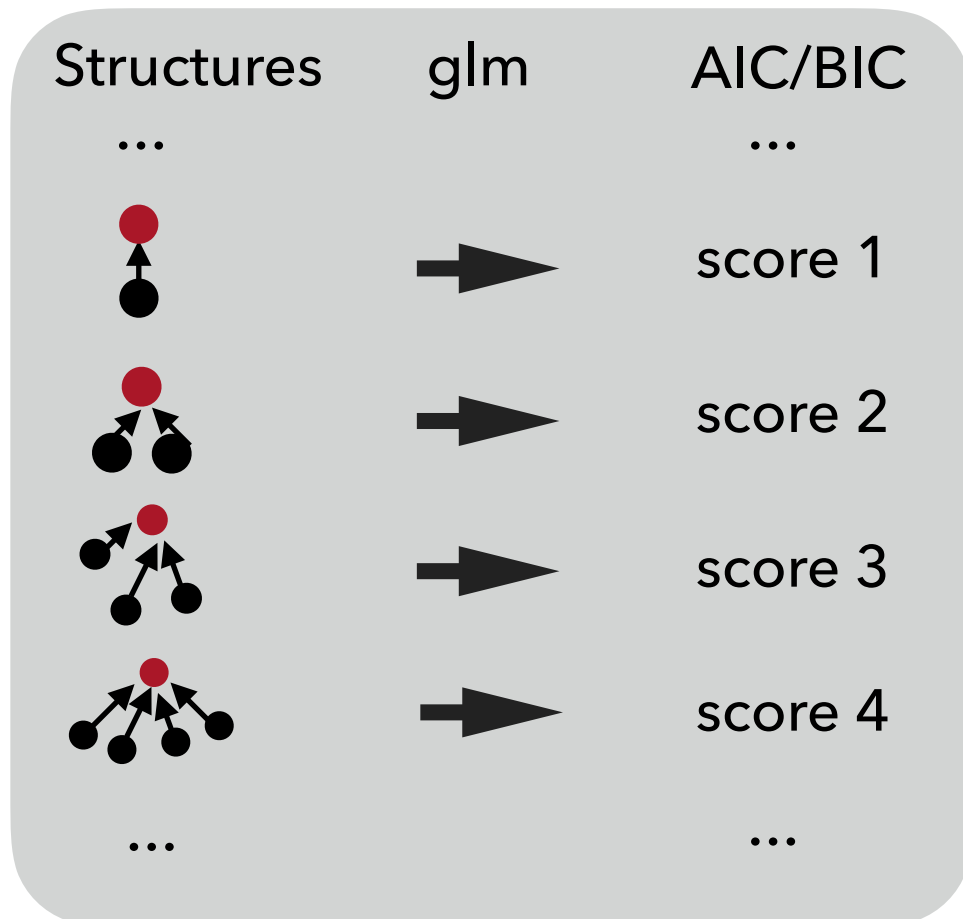
- ▶ *Heuristic approaches / Greedy search*
 - ▶ Hill-climbing (with possibly random restarts/stochastics ...)
 - ▶ Tabu search ([Glover, 1986](#))
 - ▶ Simulated annealing ([Kirkpatrick et al, 1983](#))
 - ▶ Plus an entire zoo of methods ...
- ▶ *Exact search*
 - ▶ Exact node ordering ([Koivisto et al. , 2004](#))
 - ▶ Learning with cutting planes ([Cussens, 2012](#))



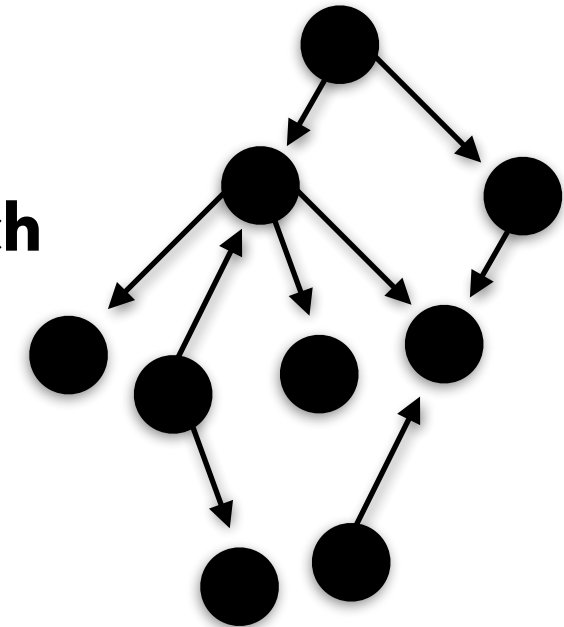
Scores

- ▶ Decomposability!
- ▶ Discrete BNs:
 - ▶ Bayesian-Dirichlet: **BDeu** ([Heckerman et al. ,1995](#))
- ▶ Score equivalence for additive regression framework:
 - ▶ **Bayesian based scores:** not always score equivalent due to the prior!
 - ▶ **Information theoretic scores:** BIC asymptotically score equivalent

Search and score algorithm

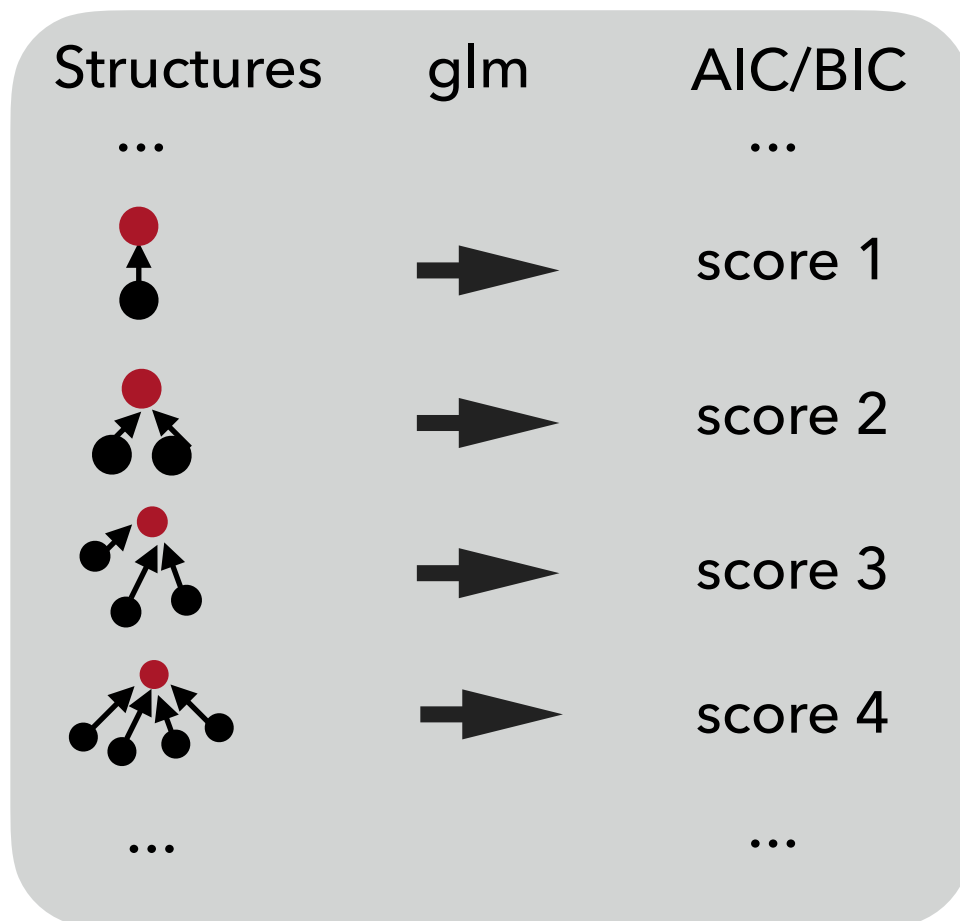


Exact or heuristic search

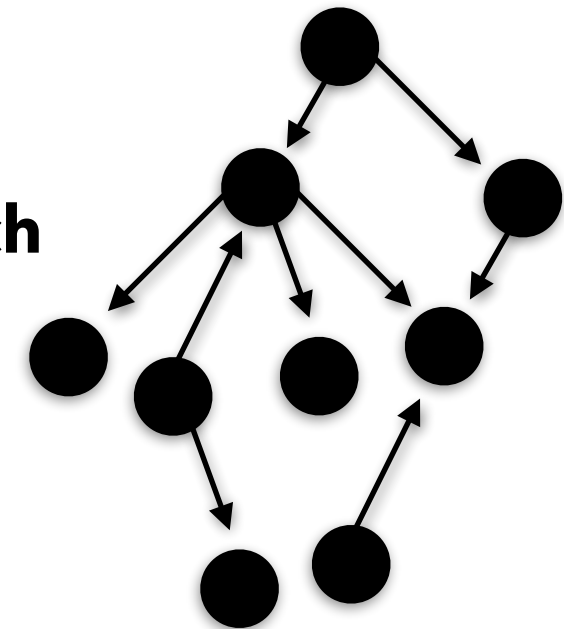


Bayesian network with
highest posterior
probability

Search and score algorithm



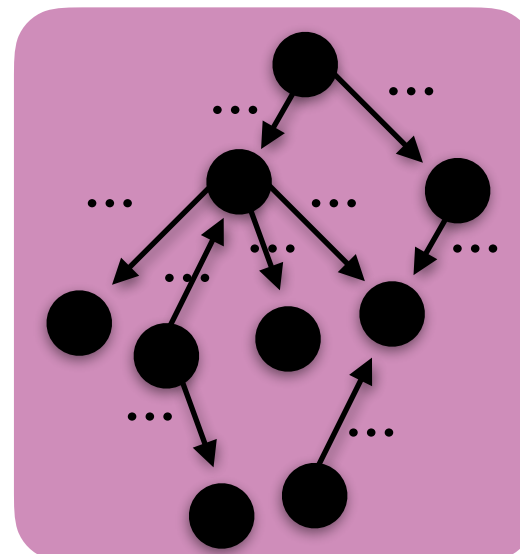
Exact or heuristic search



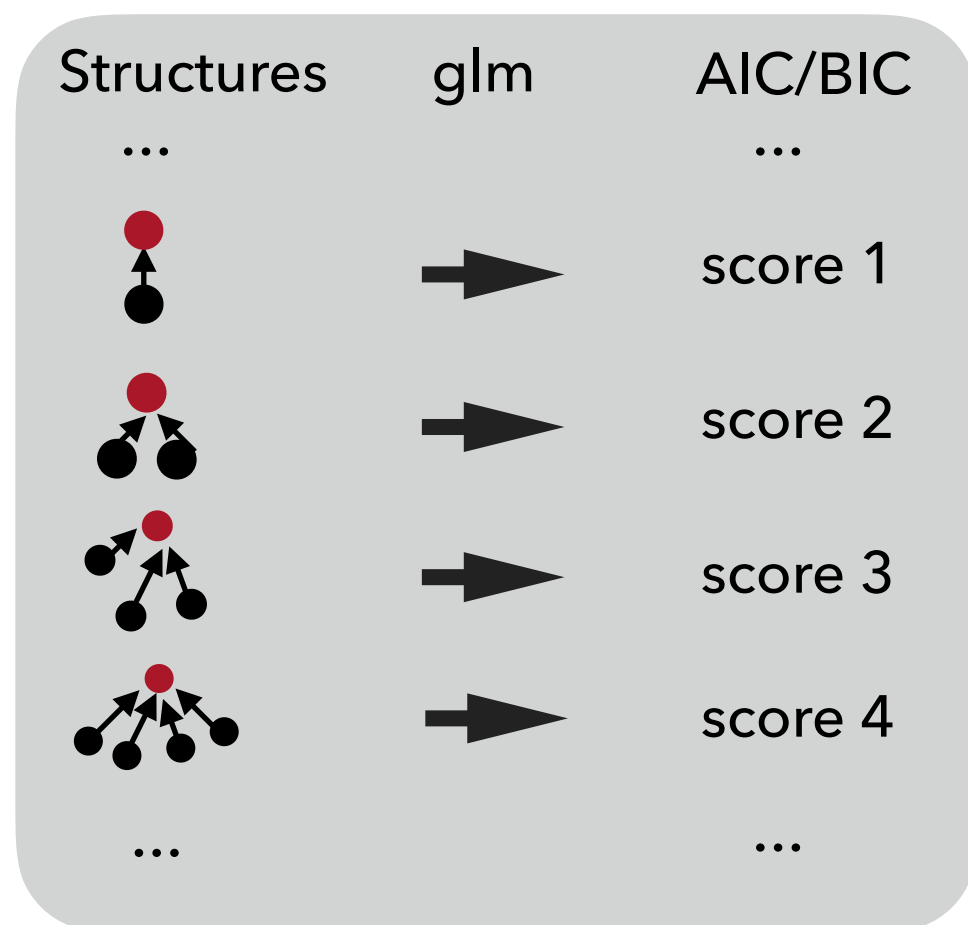
Bayesian network with
highest posterior
probability

Parameter estimation

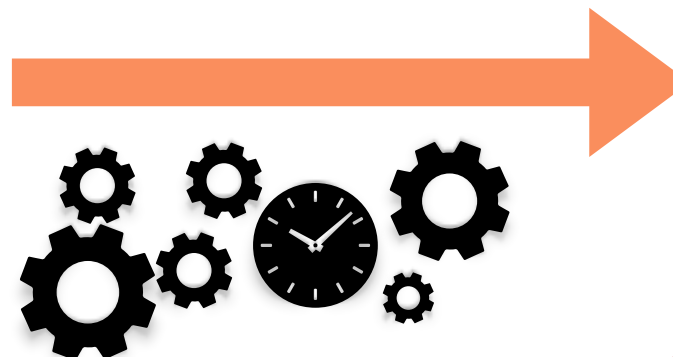
- ▶ compute marginal posterior density
- ▶ regression estimate



Search and score algorithm

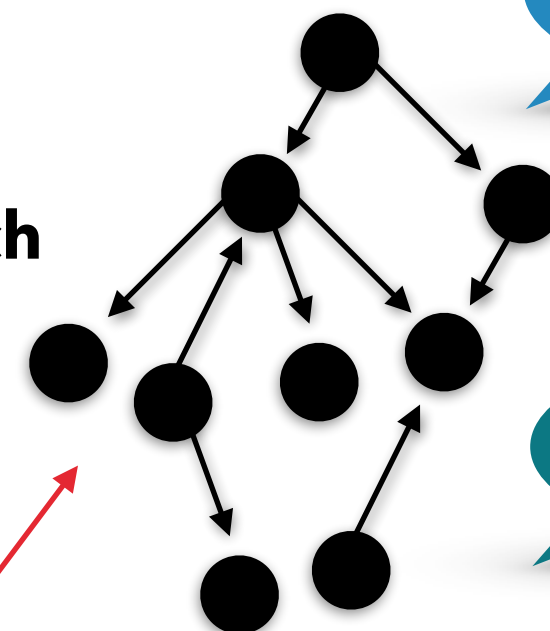


Exact or heuristic search



Causality!

*Ban/Retain
structures*



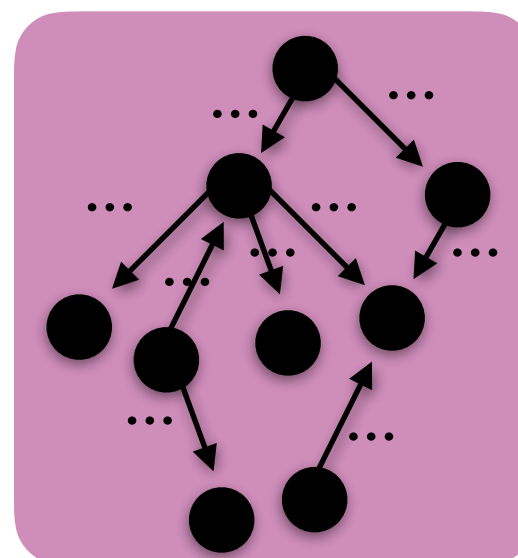
Adjustment

Random effect

Bayesian network with
highest posterior
probability

Parameter estimation

- ▶ compute marginal posterior density
- ▶ regression estimate



Using R

`buildscorecache()`

`mostprobable()`

`fitabn()`

CAUSAL THINKING VERSUS ACAUSAL THINKING

- ▶ Strong assumptions ... but common in statistics, no?
- ▶ *"It seems that if conditional independence judgements are byproducts of stored causal relationships, then tapping and representing those relationships directly would be a more natural and more reliable way of expressing what we know or believe about the world. This is indeed the philosophy behind causal Bayesian networks."* (Pearl, 2009)
- ▶ The **do-calculus**
 - ▶ **Interventions**
 - ▶ In epidemiology: **Randomised Controlled Trial**
- ▶ So ... BN is a nice framework to treat causal and acausal thinking

R CODE: SOFTWARE IMPLEMENTATION

Popular R packages (available on [CRAN](#))

bnlearn

- ▶ Learning via constraint-based and score-based algorithms (many!)

pcalg

- ▶ Robust estimation of CPDAG via the PC-Algorithm

deal

- ▶ Learning BNs with mixed (discrete and continuous) variables

catnet

- ▶ Discrete BNs using likelihood-based criteria

abn

- ▶ Learning BNs with mixed (discrete, continuous, Poisson) variables
- ▶ Score based methods: Bayesian and frequentist estimation
- ▶ Exact and heuristic search
- ▶ Link strength

Disclaimer: I am author and maintainer of the abn R package. I will use it for the example part.

VARRANK

System epidemiology

- ▶ Typically the set of possible variables is formidable
 - ▶ The classical approach for variable selection is based on prior scientific knowledge (29%)¹
 - ▶ Change of estimate (18%)¹
 - ▶ Stepwise model selection (16%)¹

No prior model?

Not one outcome experiment?

varrank

Variable ranking for better time allocation

- ▶ Variable ranking based on a set of variable of importance
- ▶ Model free. Based on information theory metrics
- ▶ Mixture of variables (continuous and discrete). Discretisation through rule/clustering

VARRANK

MAXIMUM RELEVANCE MINIMUM REDUNDANCY

f_i candidate feature to be ranked

C set of variables of importance

S set of already selected variables

$$H(X) = \sum_{n=1}^N P(x_n) \log P(x_n)$$

Average amount of information of one RV

$$MI(X; Y) = \sum_{n=1}^N \sum_{m=1}^M P(x_n; y_m) \log \frac{P(x_n; y_m)}{P(x_n)P(y_m)}$$

Mutual dependence between two RV

Difference (mid) or quotient (miq)

Greedy search

Forward - argmax

$$\text{score}_i = \underbrace{MI(f_i; \mathbf{C})}_{\text{Relevance}} - \beta \sum_{\mathbf{S}} \underbrace{\alpha(f_i, f_s, \mathbf{C})}_{\text{Normalization}} \underbrace{MI(f_i; f_s)}_{\text{Redundancy}}$$

Backward - argmax

Discretization

Estévez and al. (2009)

$$\beta = 1/|\mathbf{S}| \text{ and } \alpha(f_i, f_s, \mathbf{C}) = \frac{1}{\min(H(f_i), H(f_s))}$$

R CODE: EXAMPLE ASIA = SYNTHETIC DATASET

Proposed by Lauritzen et al., 1988 and provided by Scutari, 2009

*"Shortness-of-breath (**dyspnoea**) may be due to **tuberculosis**, **lung cancer** or **bronchitis**, or none of them, or more than one of them. A recent visit to **Asia** increases the chances of **tuberculosis**, while **smoking** is known to be a risk factor for both **lung cancer** and **bronchitis**. The results of a single chest **X-ray** do not discriminate between **lung cancer** and **tuberculosis**, as neither does the presence or absence of **dyspnoea**."*

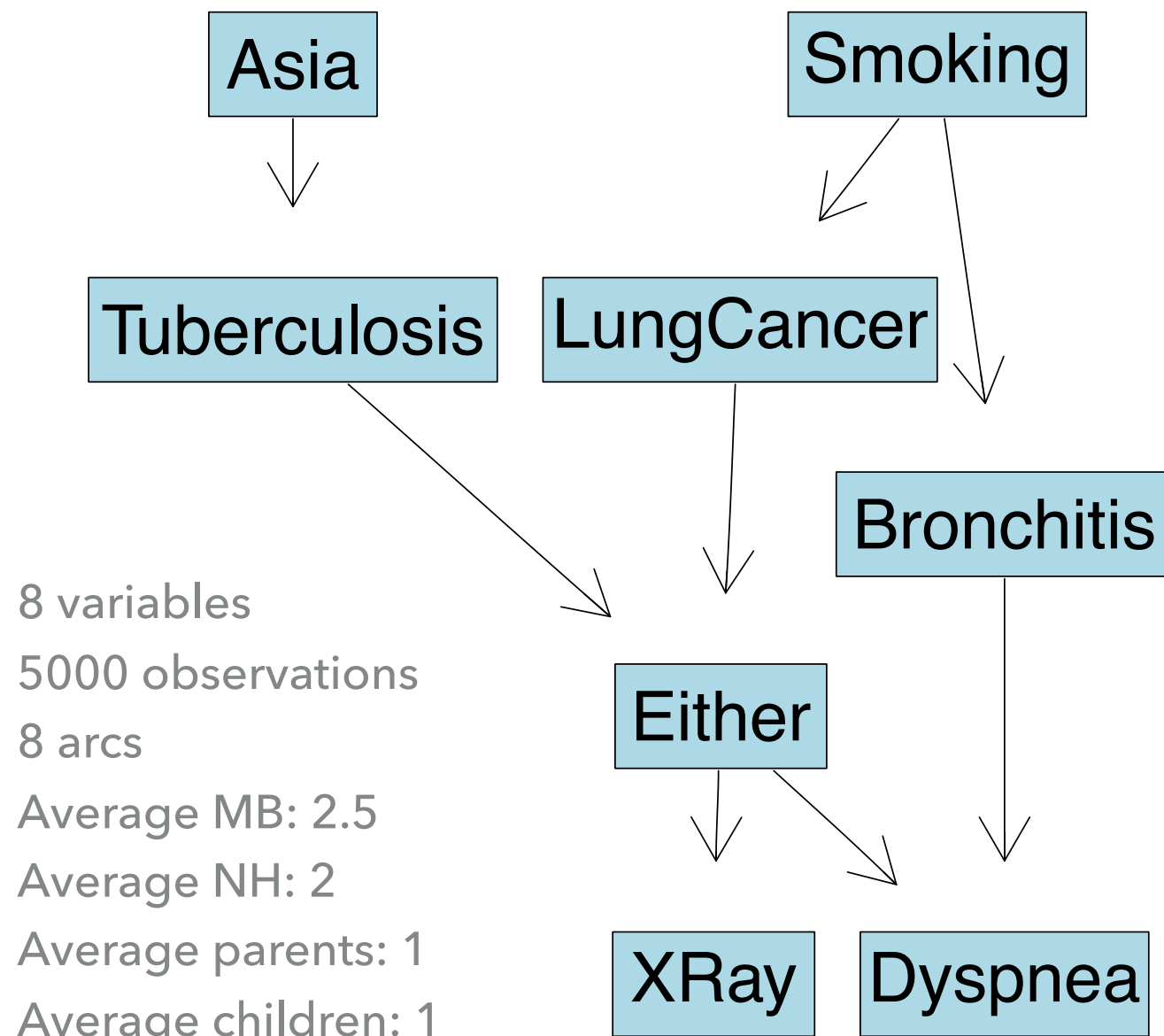
R CODE: EXAMPLE ASIA

Proposed by **Lauritzen et al., 1988** and provided by **Scutari, 2009**

"Shortness-of-breath (*dyspnoea*) may be due to *tuberculosis*, *lung cancer* or *bronchitis*, or none of them, or more than one of them. A recent visit to *Asia* increases the chances of *tuberculosis*, while *smoking* is known to be a risk factor for both *lung cancer* and *bronchitis*. The results of a single chest *X-ray* do not discriminate between *lung cancer* and *tuberculosis*, as neither does the presence or absence of *dyspnoea*."

```
##defining distributions
dist = list(Asia = "binomial",
  Smoking = "binomial",
  Tuberculosis = "binomial",
  LungCancer = "binomial",
  Bronchitis = "binomial",
  Either = "binomial",
  XRay = "binomial",
  Dyspnea = "binomial")

#plot BN
plotabn(dag.m = ~Asia|Tuberculosis +
  Tuberculosis|Either +
  Either|XRay:Dyspnea +
  Smoking|Bronchitis:LungCancer +
  LungCancer|Either +
  Bronchitis|Dyspnea,
data.dists = dist,
edgedir = "cp",
fontsize.node = 30,
edge.arrowwise = 3)
```

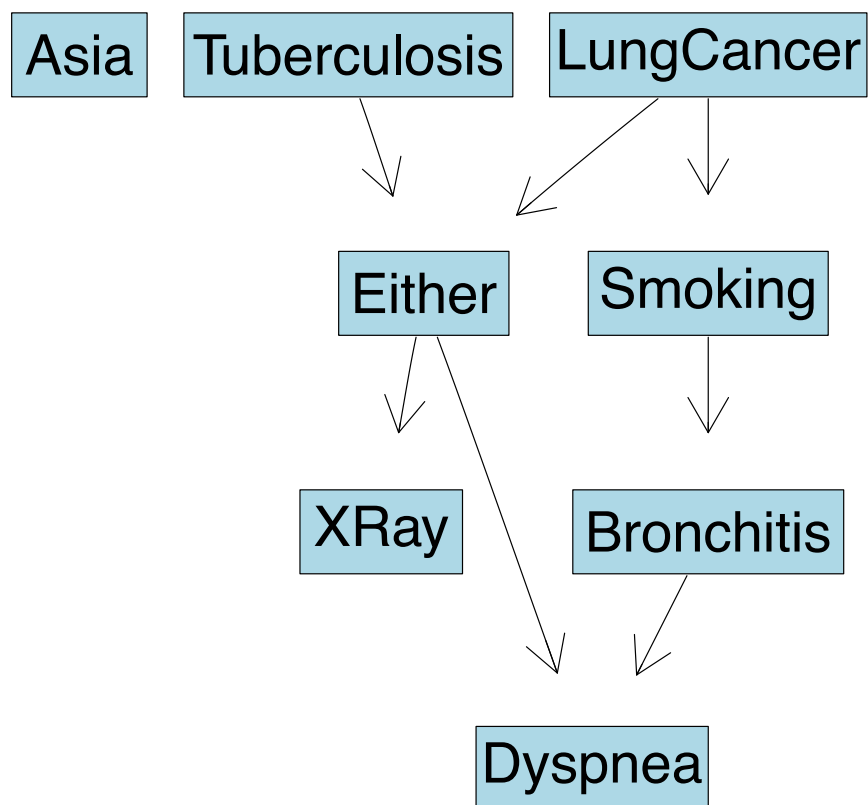


ASIA: SCORE BASED ALGORITHM

```
##=====
##score based algorithm
##=====

#loglikelihood score
bsc.compute <- buildscorecache(data.df = asia,
                              data.dists = dist,
                              max.parents = 2)

dag <- mostprobable(score.cache = bsc.compute)
plotabn(dag.m = dag, data.dists = dist, fontsize.node = 30, edge.arrowwise = 3)
```



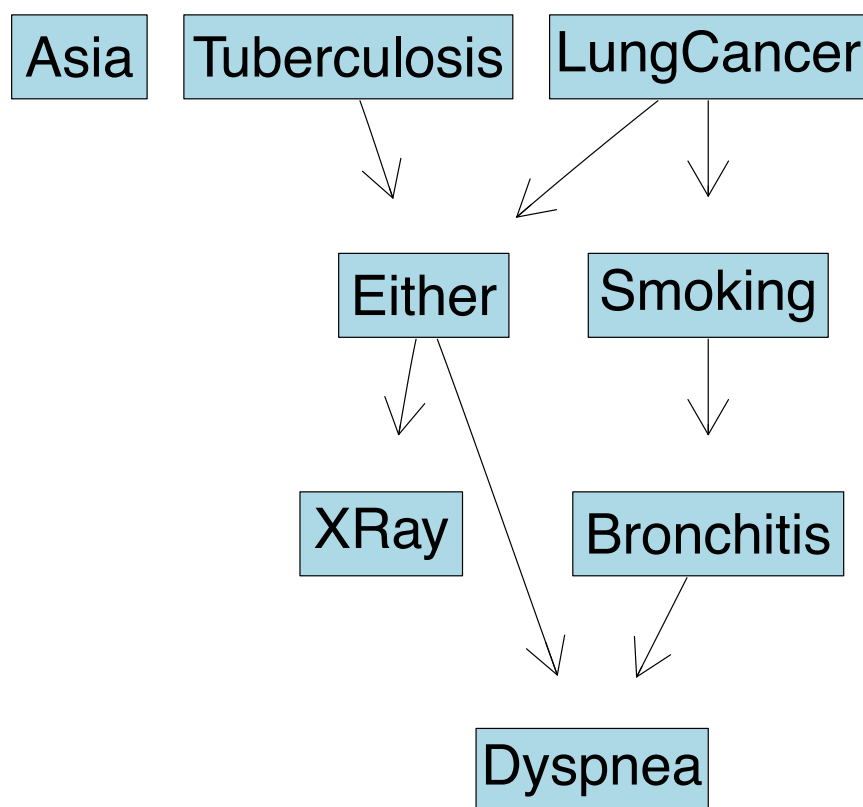
ASIA: SCORE BASED ALGORITHM

```
##=====
##score based algorithm
##=====

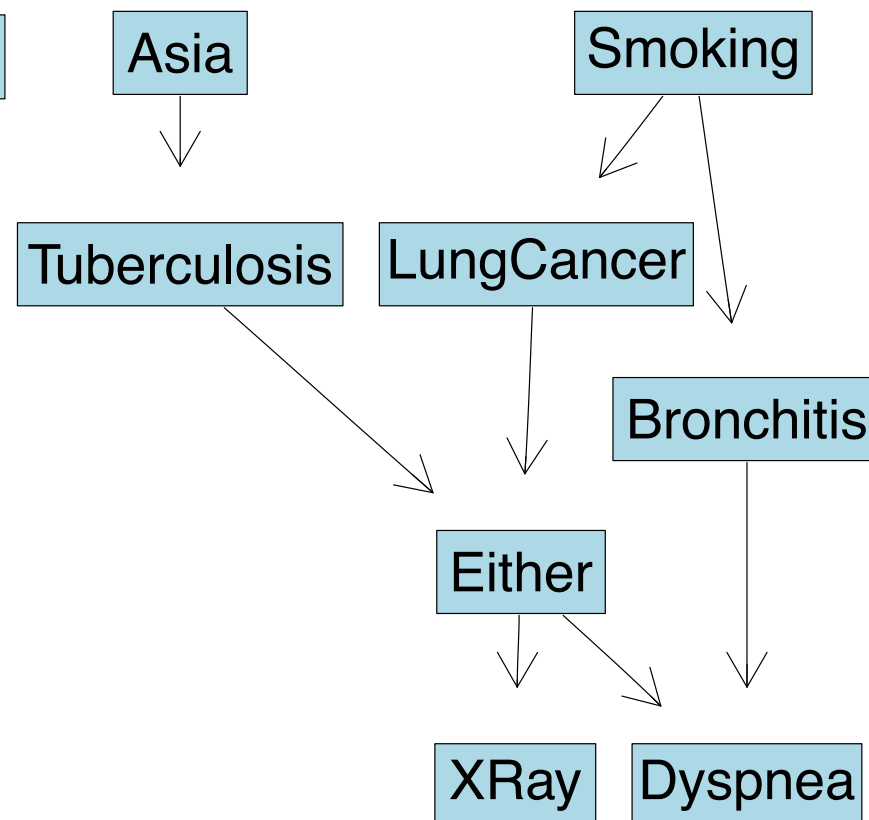
#loglikelihood score
bsc.compute <- buildscorecache(data.df = asia,
                              data.dists = dist,
                              max.parents = 2)

dag <- mostprobable(score.cache = bsc.compute)
plotabn(dag.m = dag, data.dists = dist, fontsize.node = 30, edge.arrowwise = 3)
```

Learned



Truth



ASIA: SCORE BASED ALGORITHM

```
##=====
##score based algorithm
##=====

#loglikelihood score
bsc.compute <- buildscorecache(data.df = asia,
                               data.dists = dist,
                               max.parents = 2)

dag <- mostprobable(score.cache = bsc.compute)
plotabn(dag.m = dag, data.dists = dist, fontsize.node = 30, edge.arrows = FALSE)
```

```
> compareDag(ref = t(dag.adj),
+            test = dag)
$TPR
[1] 0.75

$FPR
[1] 0.01785714

$Accuracy
[1] 0.953125

$FDR
[1] 0.2857143

$`G-measure`
[1] 0.8017837

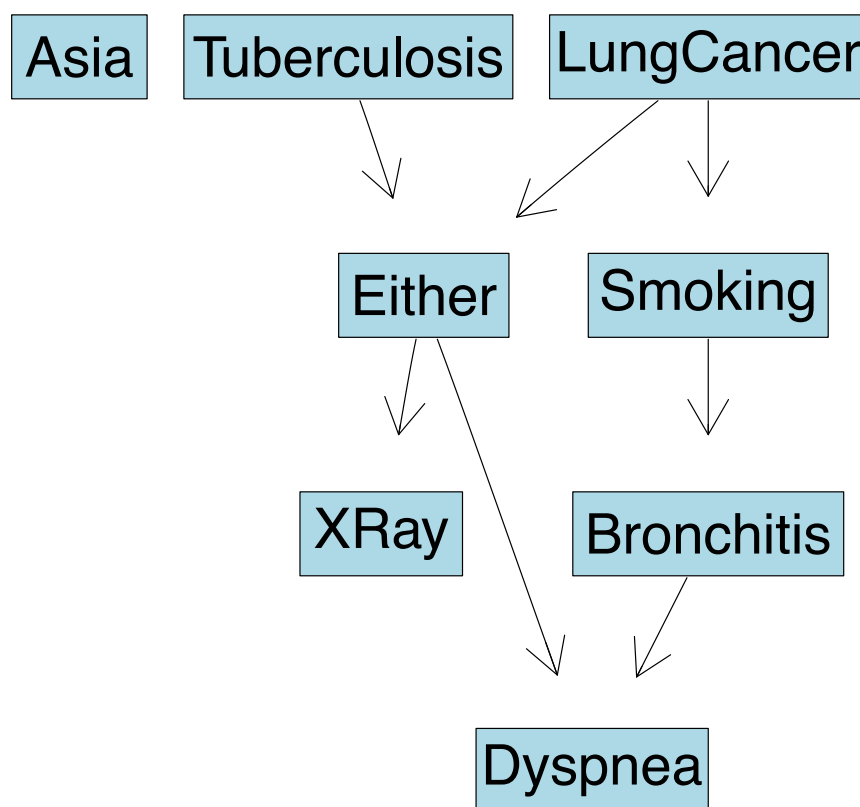
$`F1-score`
[1] 44.8

$PPV
[1] 0.8571429

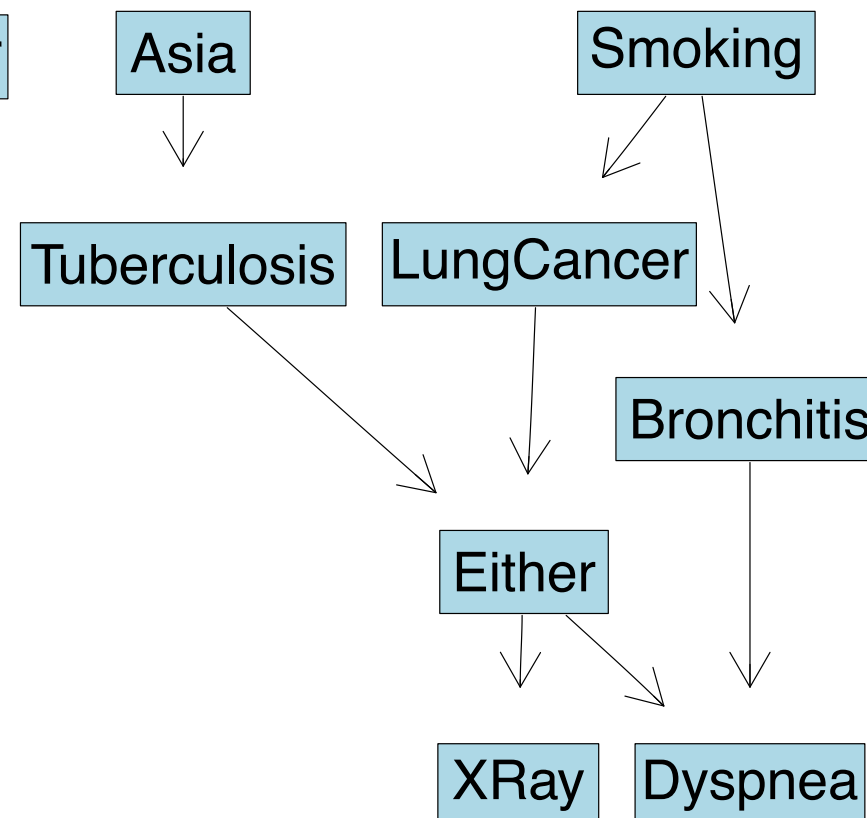
$FOR
[1] 0.2857143

$`Hamming-distance`
[1] 3
```

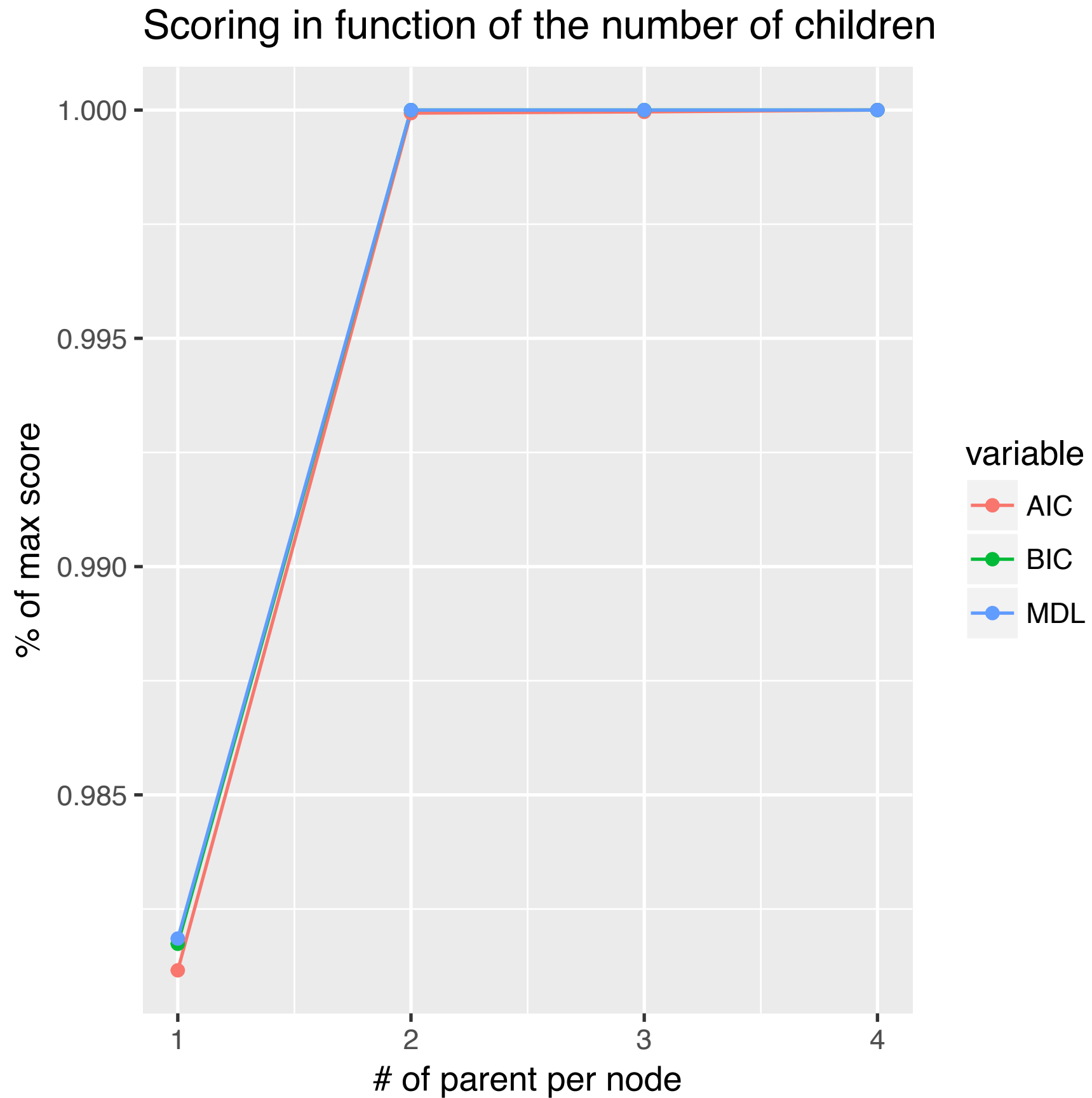
Learned



Truth



ASIA: HOW MANY PARENT ARE NEEDED?

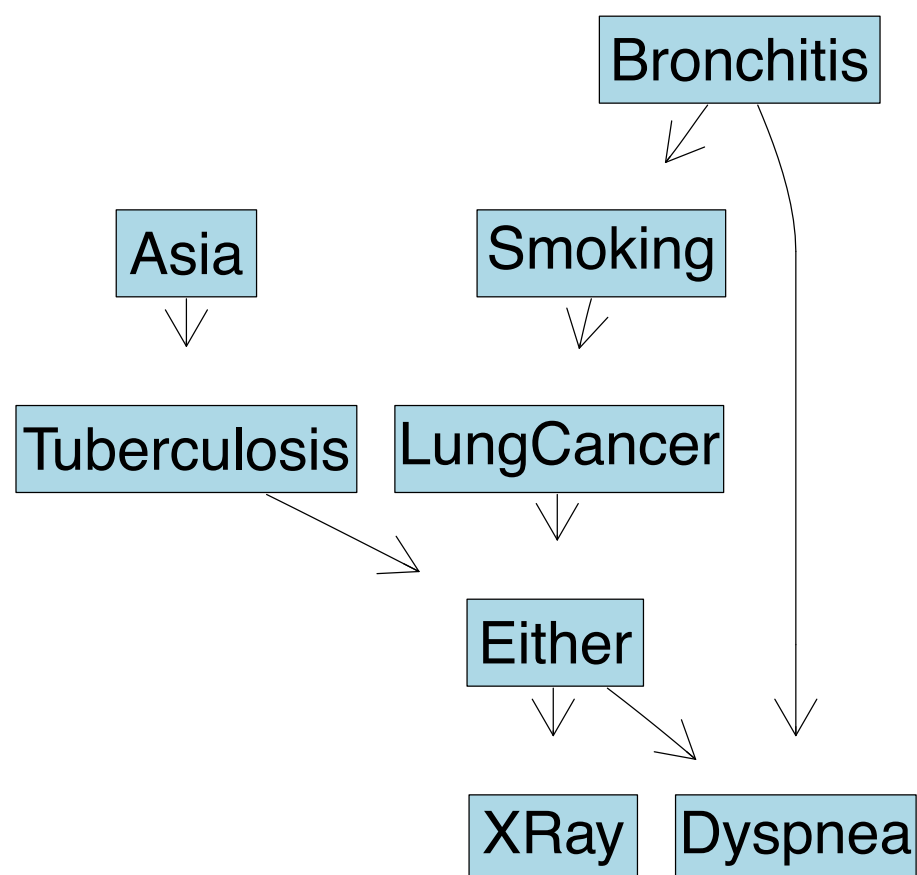


ASIA: EXTERNAL KNOWLEDGE

```
##=====
##external knowledge
##=====

##recent visit to Asia increases risk of tuberculosis
bsc.compute <- buildscorecache.mle(data.df = asia,
                                   data.dists = dist,
                                   max.parents = 2,
                                   dag.retained = ~Tuberculosis|Asia)

dag <- mostprobable(score.cache = bsc.compute,score = "bic")
plotabn(dag.m = dag,data.dists = dist, fontsize.node = 30, edge.arrowwise = 3)
```



ASIA: EXTERNAL KNOWLEDGE

```
##=====
##external knowledge
##=====

##recent visit to Asia increases risk of tuberculosis
bsc.compute <- buildscorecache.mle(data.df = asia,
                                   data.dists = dist,
                                   max.parents = 2,
                                   dag.retained = ~Tuberculosis|Asia)

dag <- mostprobable(score.cache = bsc.compute, score = "bic")
plotabn(dag.m = dag, data.dists = dist, fontsize.node = 30, edge.arrow
```

```
> compareDag(ref = t(dag.adj),
+            test = (dag))
$TPR
[1] 0.875

$FPR
[1] 0.01785714

$Accuracy
[1] 0.96875

$FDR
[1] 0.125

$`G-measure`
[1] 0.875

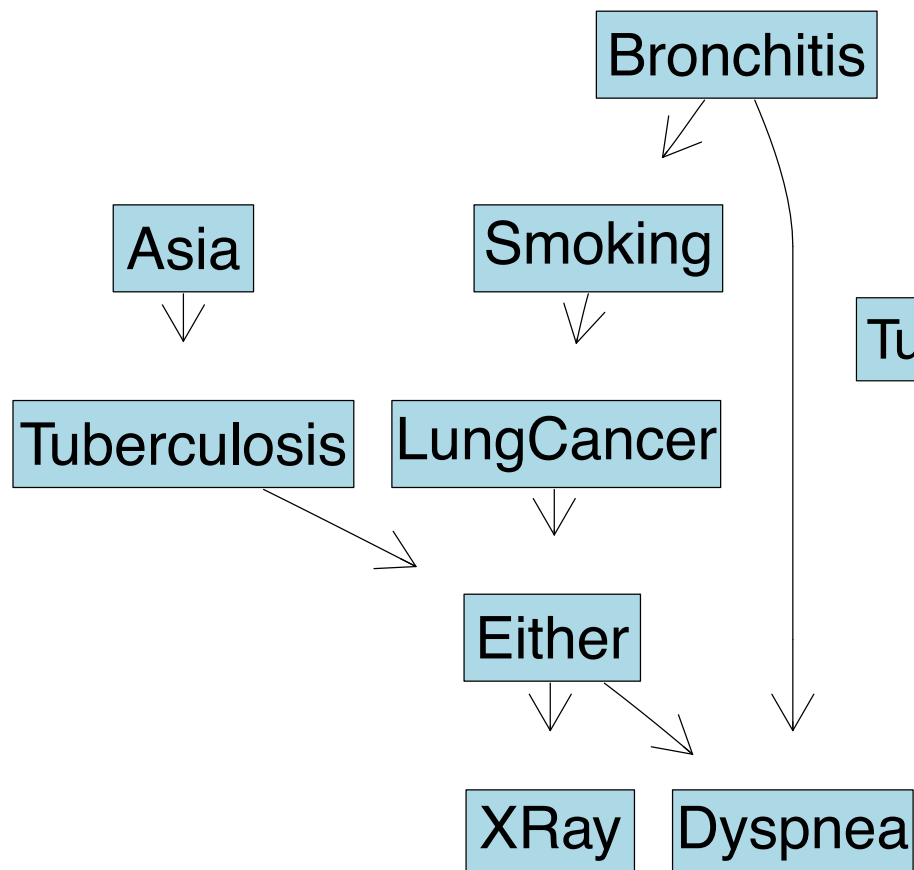
$`F1-score`
[1] 56

$PPV
[1] 0.875

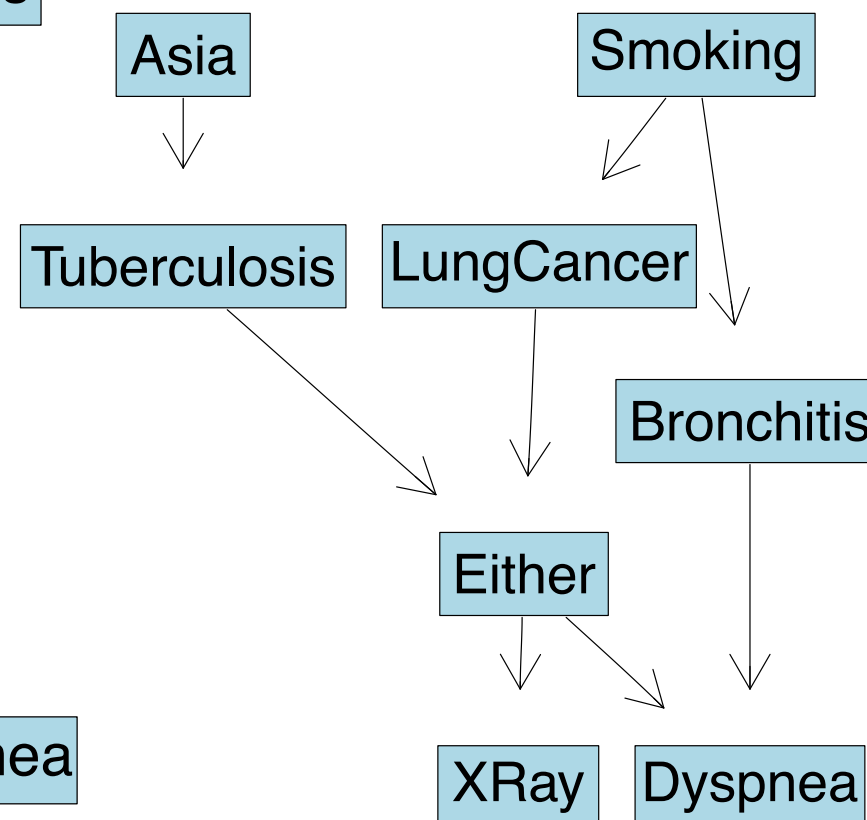
$FOR
[1] 0.125

$`Hamming-distance`
[1] 2
```

Learned



Truth

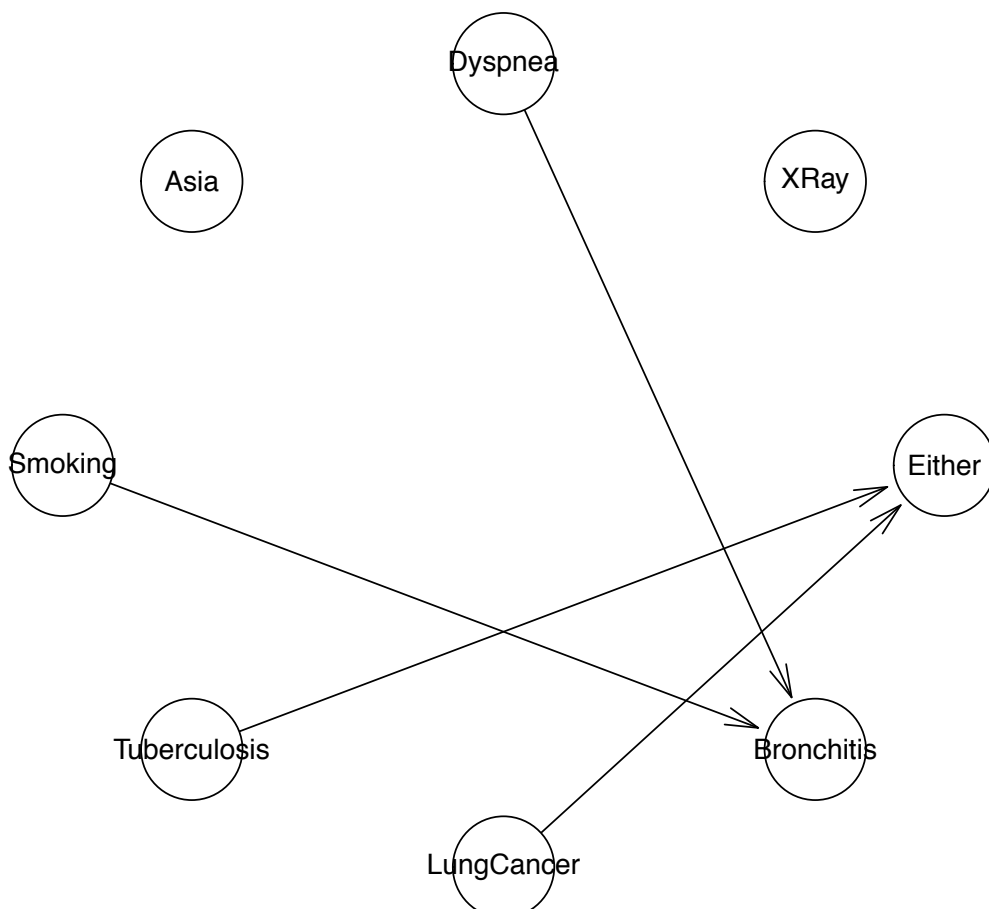


ASIA: CONSTRAINT-BASED LEARNING

```
##=====
## constraint-based algorithm
##=====

bn.gs <- gs(asia)
plot(bn.gs)

bn.iamb <- iamb(asia)
plot(bn.iamb)
```



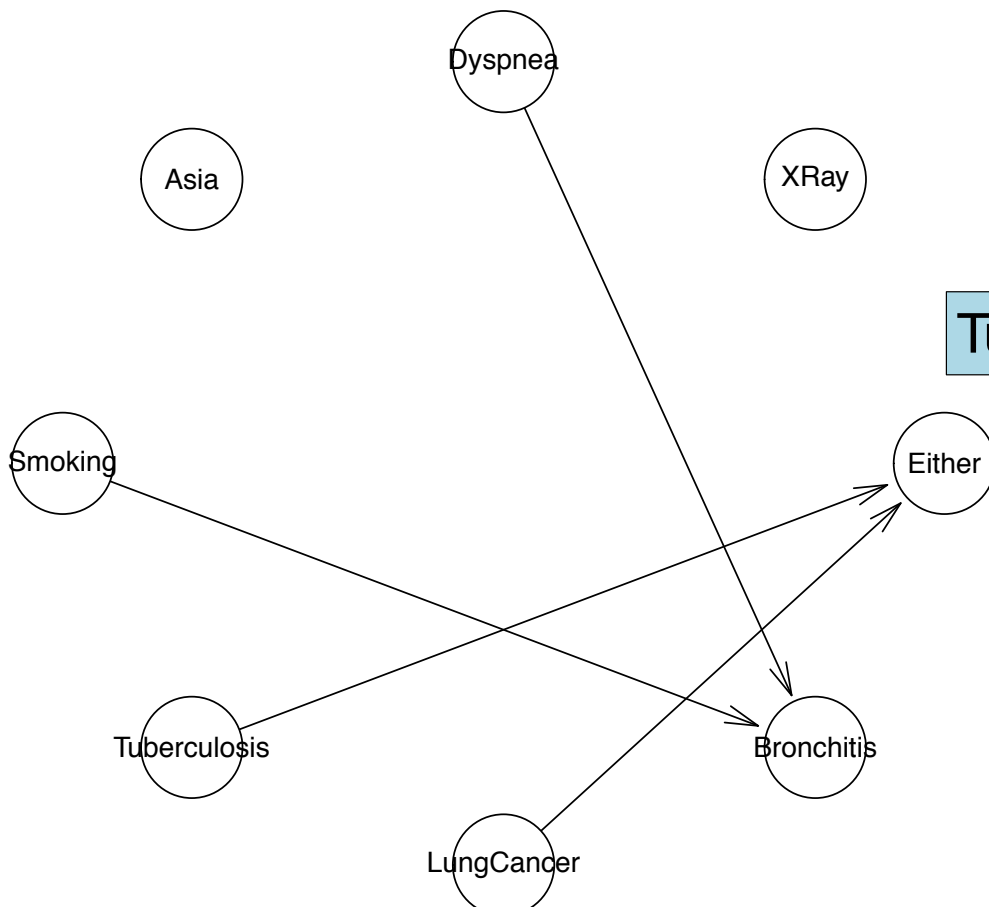
ASIA: CONSTRAINT-BASED LEARNING

```
##=====
## constraint-based algorithm
##=====

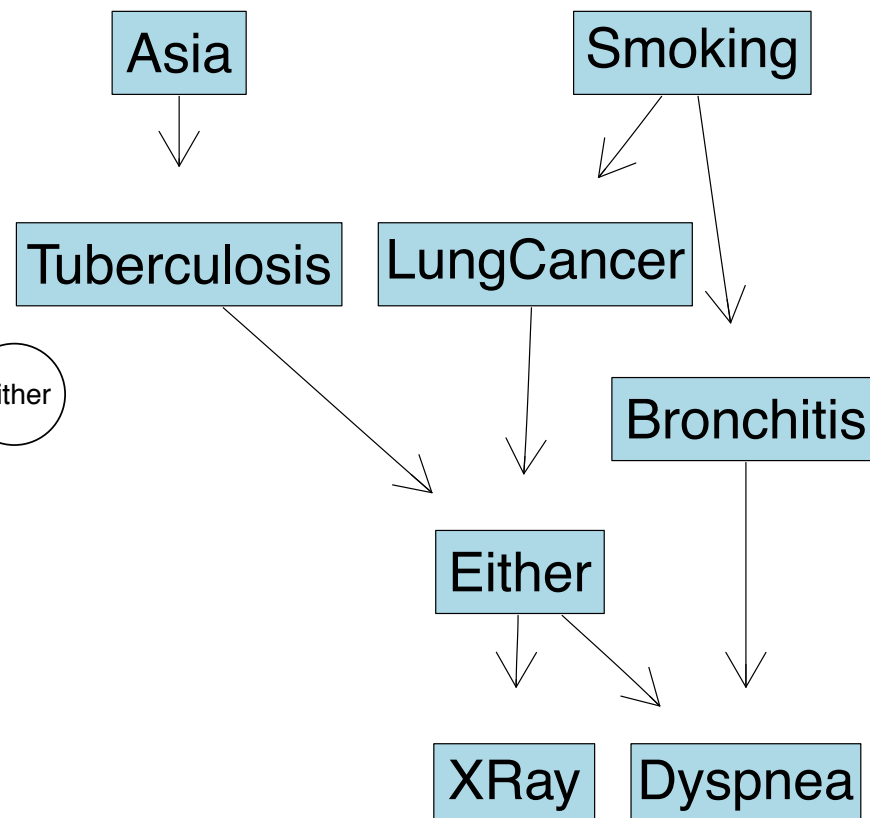
bn.gs <- gs(asia)
plot(bn.gs)

bn.iamb <- iamb(asia)
plot(bn.iamb)
```

Learned



Truth



```
> compareDag(ref = t(dag),
+             test = amat(bn.gs))
$TPR
[1] 0.4285714

$FPR
[1] 0.01754386

$Accuracy
[1] 0.921875

$FDR
[1] 1

$`G-measure`
[1] 0.5669467

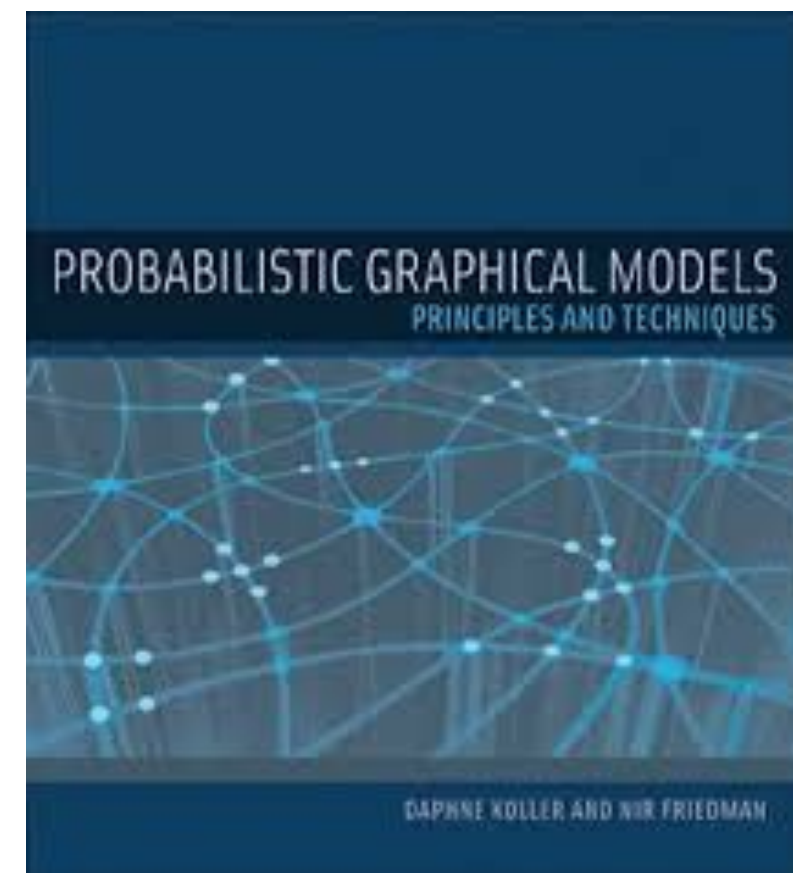
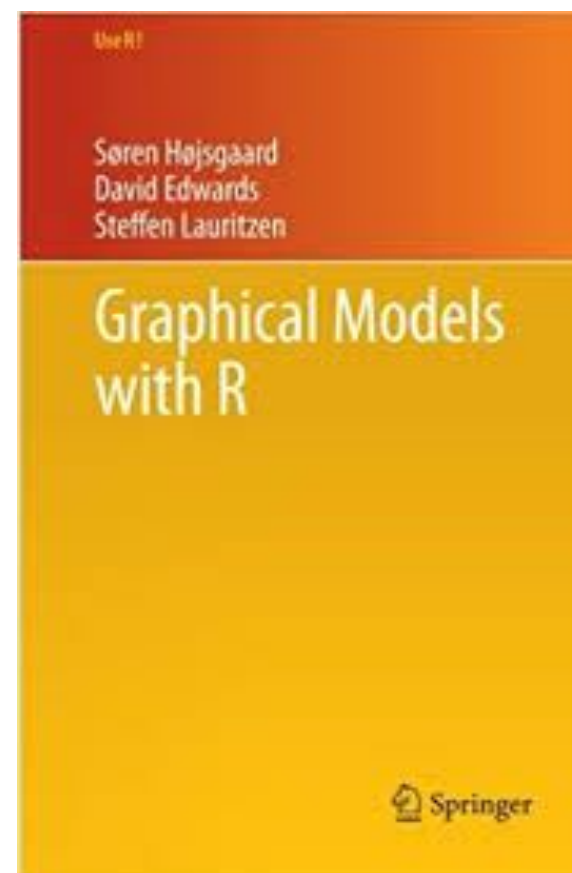
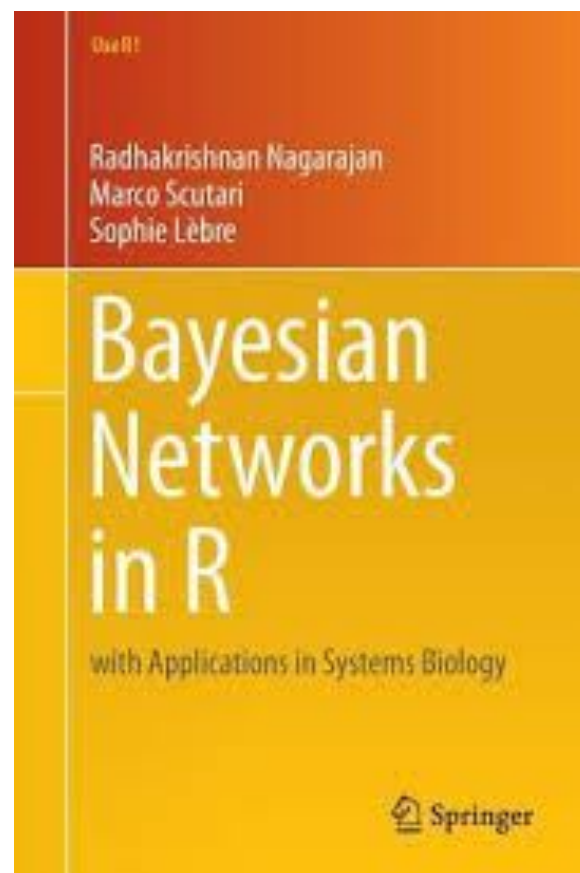
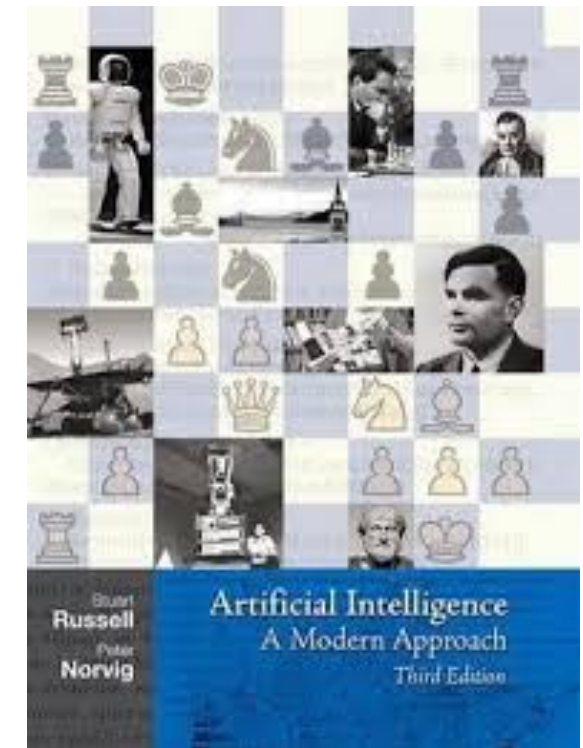
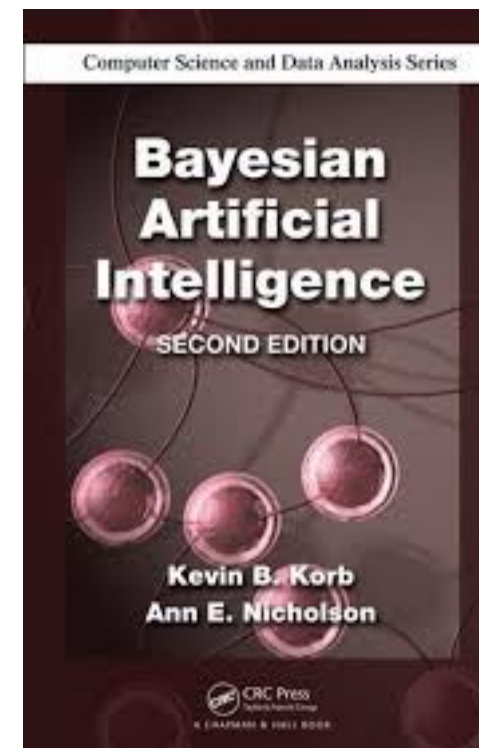
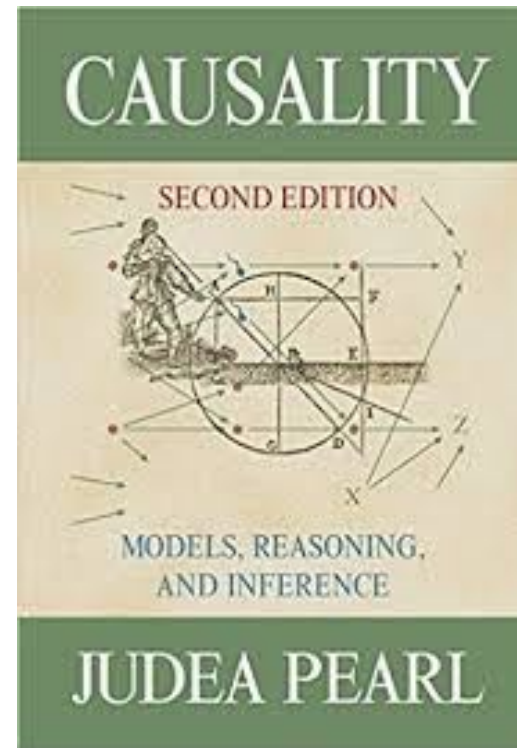
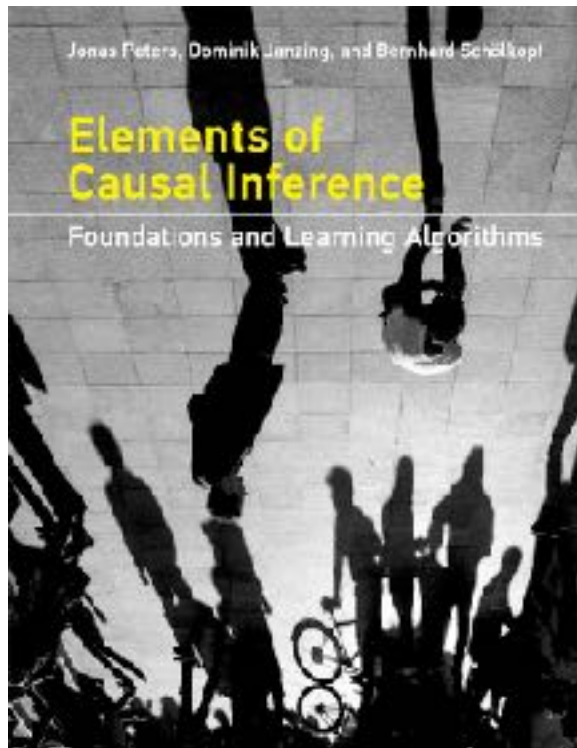
$`F1-score`
[1] 15.27273

$PPV
[1] 0.75

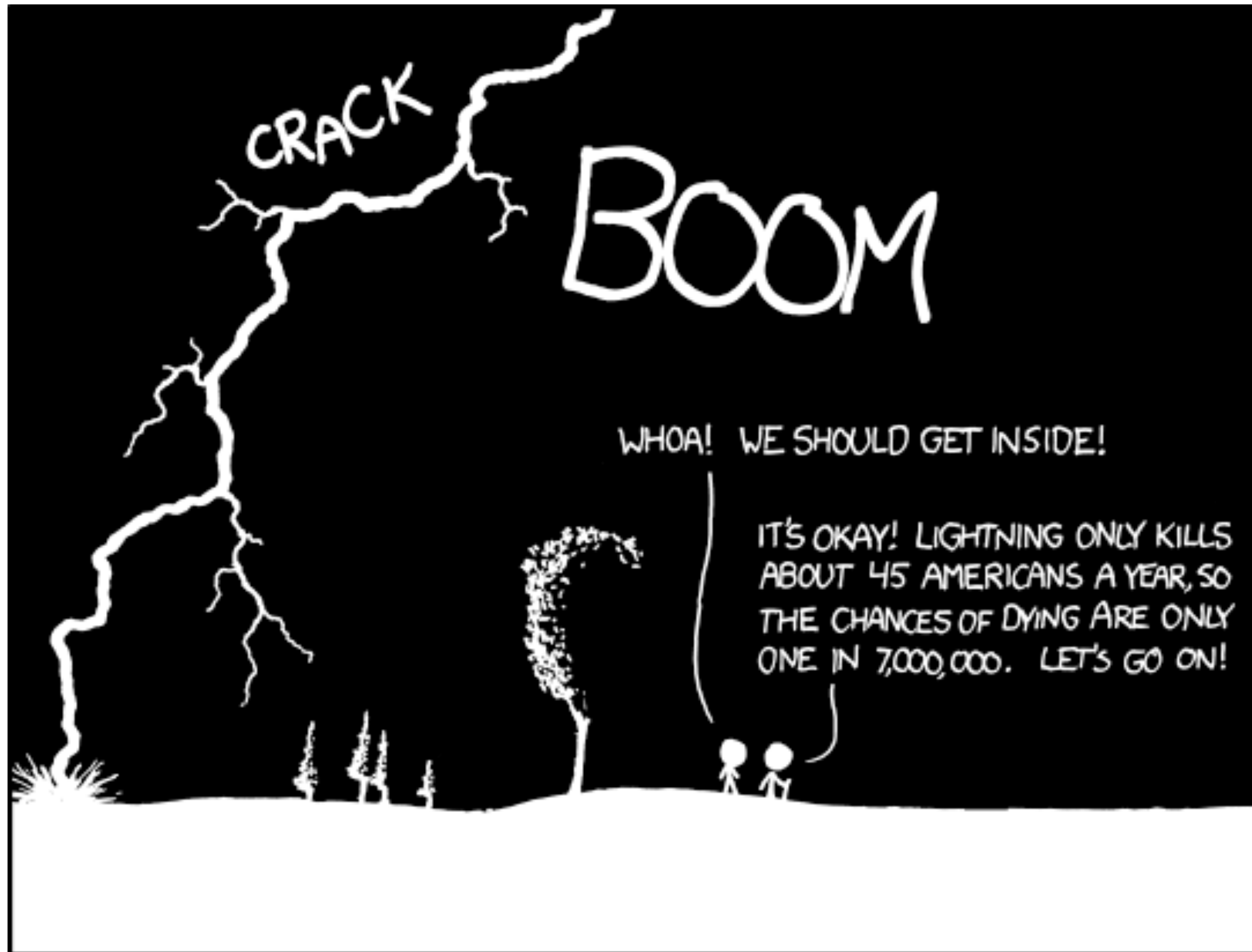
$FOR
[1] 1

$`Hamming-distance`
[1] 5
```


SELECTED BIBLIOGRAPHY



Thank you for your attention



THE ANNUAL DEATH RATE AMONG PEOPLE
WHO KNOW THAT STATISTIC IS ONE IN SIX.

Backup slides

LEARNING BAYESIAN NETWORKS

A path from A to B is **blocked** if it contains a node s.t. either

- ▶ the arrows on the path meet either head-to-tail or tail-to-tail at the node, and the node is in the set C, or
- ▶ the arrows meet head-to-head at the node, and neither the node, nor any of its descendants, are C.

If all paths from A to B are blocked, A is said to be **d-separated** from B by C.

Theorem (Verma & Pearl, 1988): A is d-separated from B by C if, and only if, the joint distribution over all variables in the graph satisfies:

$$A \perp\!\!\!\perp_G B | C$$

Link between statistical statement (conditionally independent) and a graph propriety (d-separation)

ASIA: HOW MANY PARENT ARE NEEDED?

```
res.mlik <- NULL
res.aic <- NULL
res.bic <- NULL
res.mdl <- NULL

for(i in 1:4){
  mycache.computed.mle <- buildscorecache.mle(data.df = asia,
                                              data.dists = dist,
                                              max.parents = i,
                                              dry.run = FALSE,
                                              maxit = 1000,
                                              tol = 1e-11)

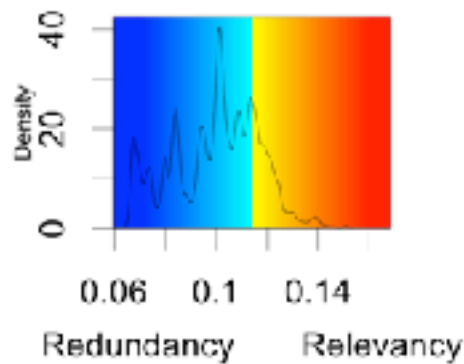
  dag <- mostprobable(score.cache = mycache.computed.mle, score = "aic")
  res.aic <- rbind(res.aic, fitabn.mle(dag.m = dag, data.df = mycache.computed.mle$data.df, data.dists = dist)$aic)
  dag <- mostprobable(score.cache = mycache.computed.mle, score = "bic")
  res.bic <- rbind(res.bic, fitabn.mle(dag.m = dag, data.df = mycache.computed.mle$data.df, data.dists = dist)$bic)
  dag <- mostprobable(score.cache = mycache.computed.mle, score = "mdl")
  res.mdl <- rbind(res.mdl, fitabn.mle(dag.m = dag, data.df = mycache.computed.mle$data.df, data.dists = dist)$mdl)
}

library(ggplot2)
library(reshape)
scoring <- data.frame(AIC = max(-res.aic)/-res.aic, BIC = max(-res.bic)/-res.bic, MDL = max(-res.mdl)/-res.mdl, 1:4)

scoring.long <- melt(scoring, id.vars="X1.4")

ggplot(data = scoring.long, aes(x=X1.4, y=(value), group=variable, color=variable)) +
  geom_line() +
  geom_point() +
  ggtitle("Scoring in function of the number of children", subtitle = NULL) +
  xlab("# of parent per node") +
  ylab("% of max score") +
  scale_x_continuous(breaks=c(1,2,3,4,5,6,7))
```

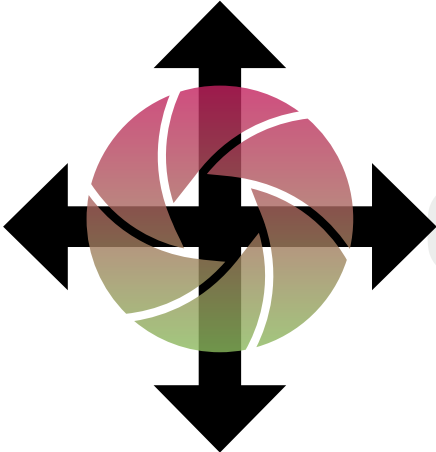
EPI: 3570 observations and 57 variables



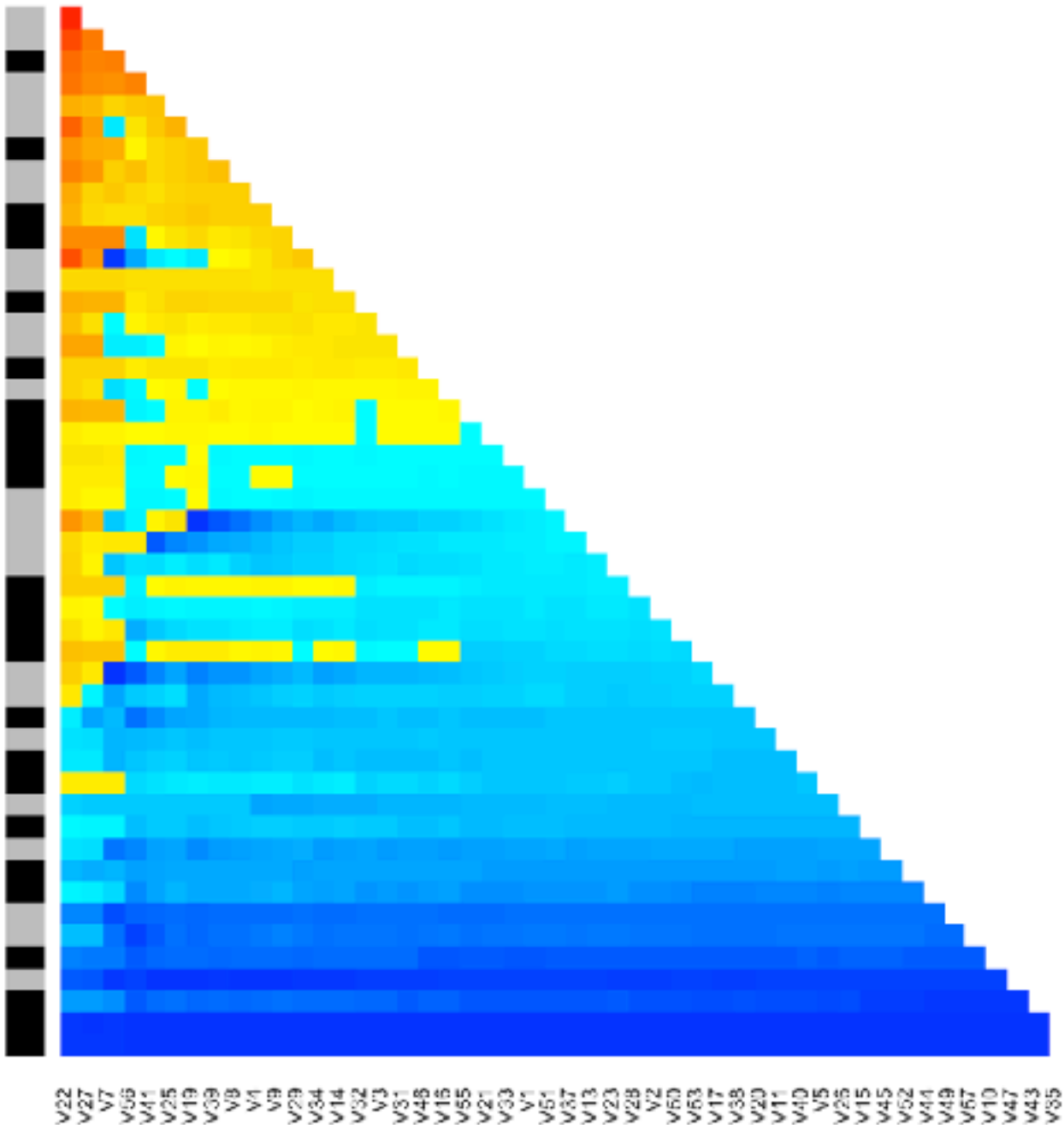
Structure of EPI:

✓ Lie scale (9 responses)

Extrovert score (24)

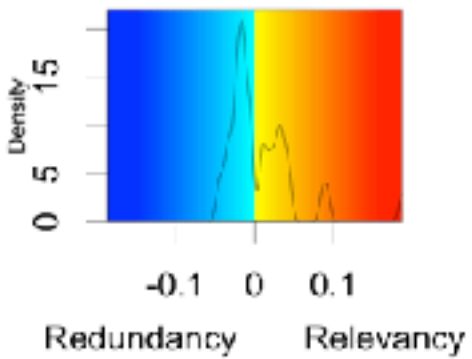


Neurotic score (24)



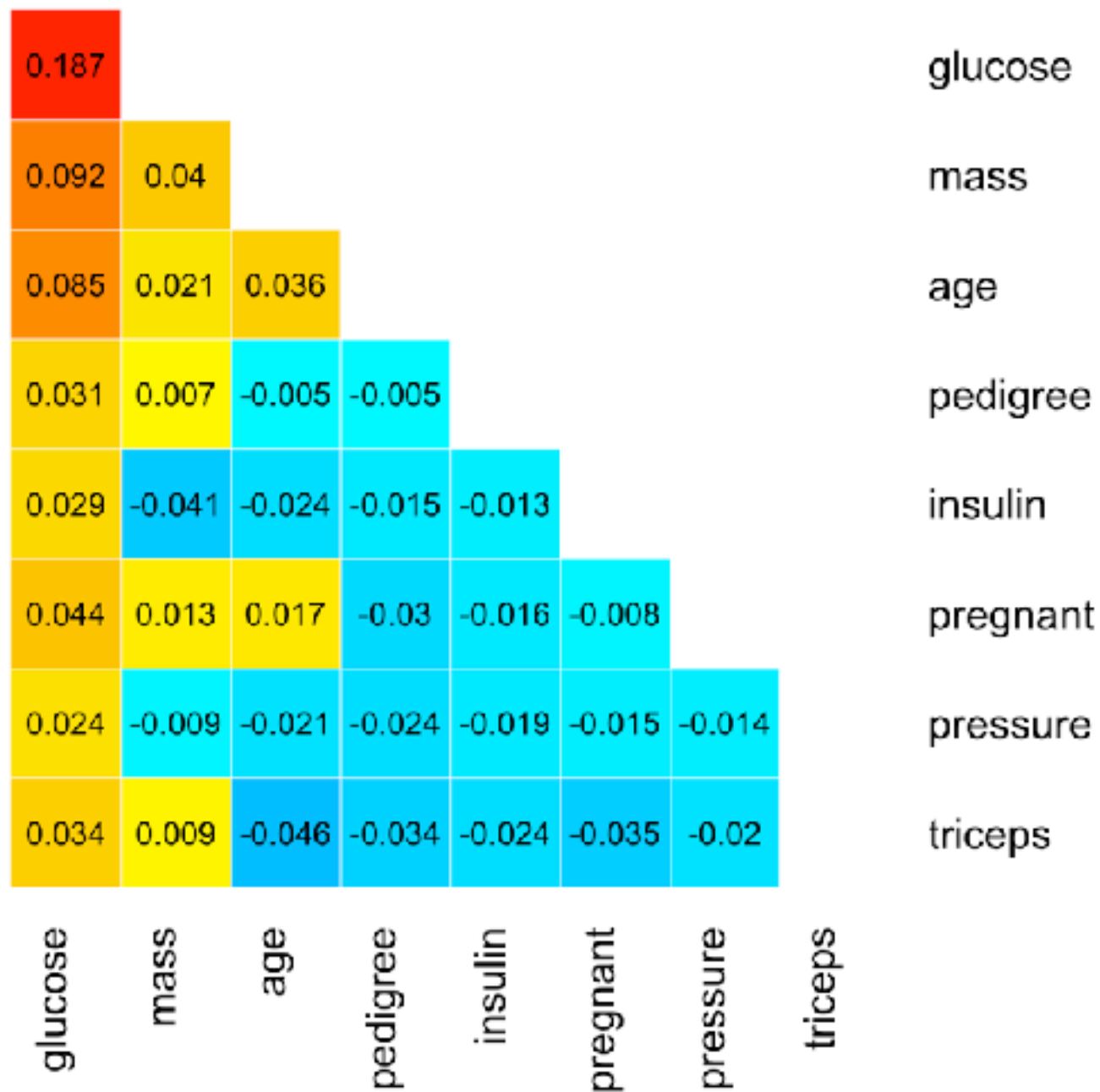
VARRANK

DIABETE



Pima Indians Diabetes Database

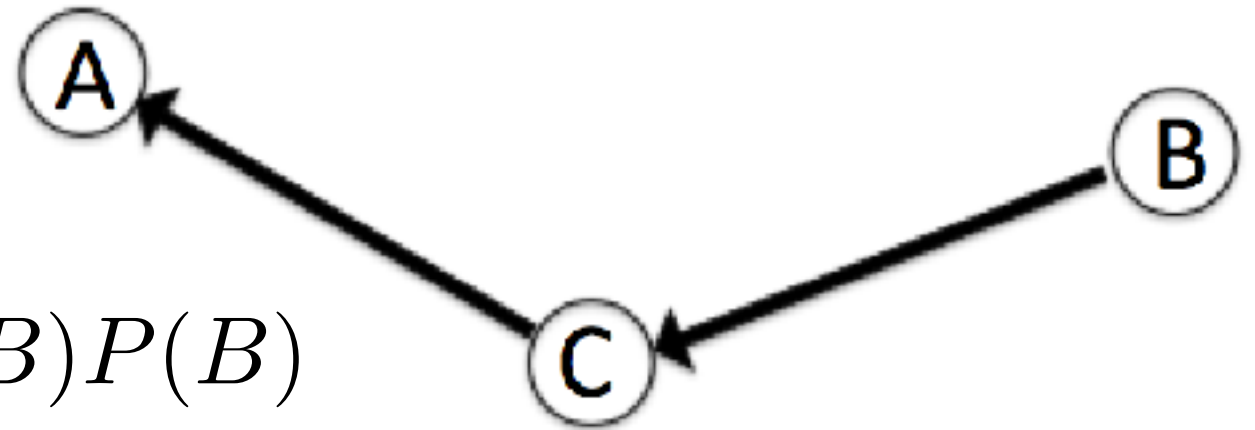
768 observations on 9 variables



Let A , B and C non intersecting subsets of nodes in a DAG G

A is **conditionally independent** of B given C if: $A \perp\!\!\!\perp_P B | C$

$$P(A, B | C) = P(A | C)P(B | C)$$



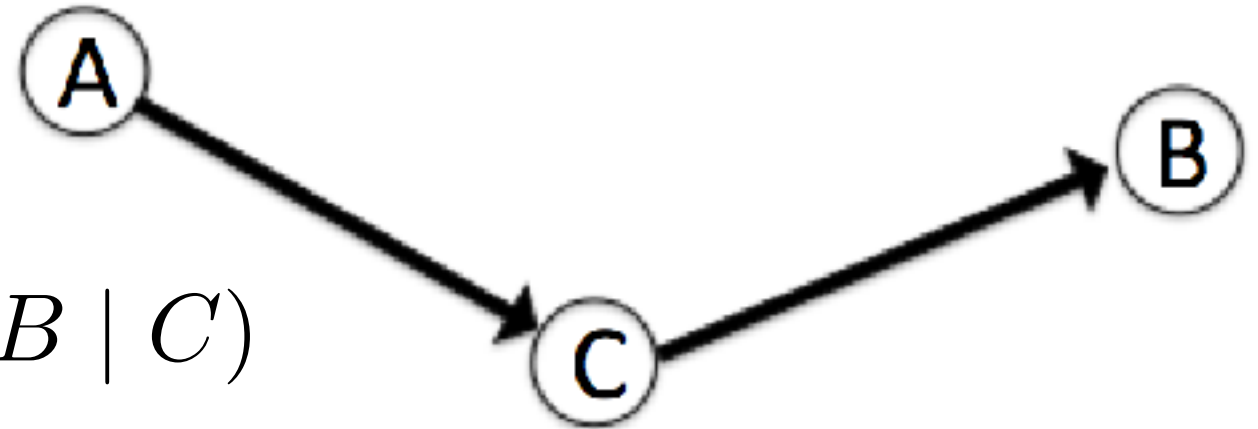
$$P(A, B, C) = P(A | C)P(C | B)P(B)$$

$$\begin{aligned} P(A, B | C) &= \frac{P(A | C)P(C | B)P(B)}{P(C)} \\ &= \frac{P(A | C)P(B, C)}{P(C)} \\ &= P(A | C)P(B | C) \end{aligned}$$

Let A , B and C non intersecting subsets of nodes in a DAG G

A is **conditionally independent** of B given C if: $A \perp\!\!\!\perp_P B | C$

$$P(A, B | C) = P(A | C)P(B | C)$$



$$P(A, B, C) = P(A)P(C | A)P(B | C)$$

$$P(A, B | C) = \frac{P(A)P(C | A)P(B | C)}{P(C)}$$

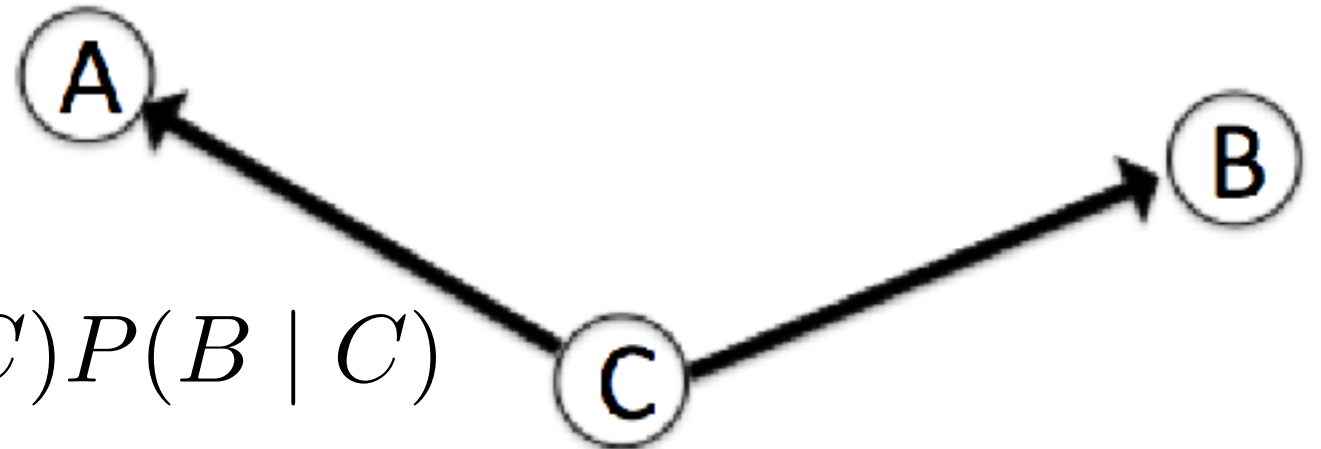
$$= \frac{P(A, C)P(B | C)}{P(C)}$$

$$= P(A | C)P(B | C)$$

Let A , B and C non intersecting subsets of nodes in a DAG G

A is **conditionally independent** of B given C if: $A \perp\!\!\!\perp_P B | C$

$$P(A, B | C) = P(A | C)P(B | C)$$



$$P(A, B, C) = P(C)P(A | C)P(B | C)$$

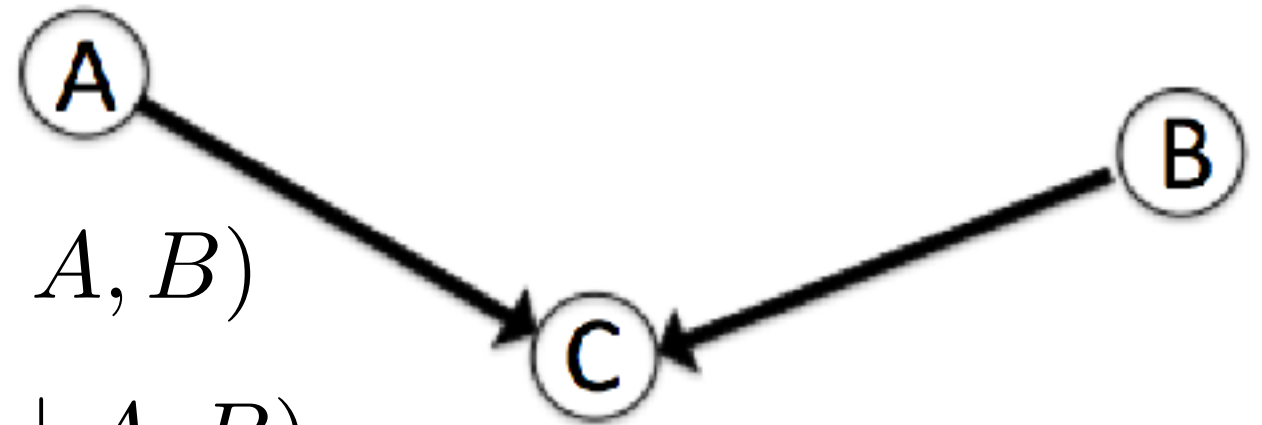
$$\begin{aligned} P(A, B | C) &= \frac{P(C)P(A | C)P(B | C)}{P(C)} \\ &= P(A | C)P(B | C) \end{aligned}$$

Let A , B and C non intersecting subsets of nodes in a DAG G

A is **conditionally independent** of B given C if: $A \perp_P B | C$

$$P(A, B | C) = P(A | C)P(B | C)$$

$$\begin{aligned} P(A, B, C) &= P(A)P(B)P(C | A, B) \\ P(A, B | C) &= \frac{P(A)P(B)P(C | A, B)}{P(C)} \\ &= \frac{P(A)P(B)P(A, B, C)}{P(A)P(B)P(C)} \\ &= P(A, B | C) \end{aligned}$$



$$A \not\perp_P B | C$$

Constraint-based algorithms

- ▶ *Inductive Causation (IC)*: ([Verma and Pearl, 1991](#))
 - ▶ Provides a framework for learning the structure of Bayesian networks using conditional independence tests in three steps
 - ▶ A major problem of the IC algorithm is that the first two steps cannot be applied to any real-world problem due to computational complexity ...
- ▶ *PC*: first practical application of the IC algorithm ([Spirtes et al., 2001](#))
 - ▶ backward selection procedure from the saturated graph
- ▶ *Grow-Shrink (GS)* ([Margaritis, 2003](#))
 - ▶ Simple forward selection MB detection approach
- ▶ *Incremental Association (IAMB)*: ([Tsamardinos et al., 2003](#))
 - ▶ two-phase selection scheme based on a forward selection followed by a backward selection of the MB

LEARNING BAYESIAN NETWORKS

- ▶ **Constraint-based** methods require a **Markov** and **faithfulness** assumption
- ▶ Conditional independencies in the distribution exactly equal the ones encoded in the DAG via **d-separation**

$$A \perp\!\!\!\perp_G B|C \begin{array}{c} \text{Markov} \\ \rightleftarrows \\ \text{Faithful} \end{array} A \perp\!\!\!\perp_P B|C$$

- ▶ **Causal sufficiency**: no unmeasured common causes

In a practical perspective:

- ▶ Testing mixture of data?
- ▶ Testing assumptions?

ASIA: KNOWN NETWORK

```
fitabn(dag.m = ~Asia|Tuberculosis+
      Tuberculosis|Either +
      Either|XRay:Dyspnea +
      Smoking|Bronchitis:LungCancer +
      LungCancer|Either +
      Bronchitis|Dyspnea,data.df = asia,data.dists = dist)$modes
```

```
fitabn.mle(dag.m = dag.adj,data.df = asia,data.dists = dist)$coef
```

```
$Asia
Asia|(Intercept) Asia|Tuberculosis
      -4.811200      1.765763

$Smoking
Smoking|(Intercept) Smoking|LungCancer Smoking|Bronchitis
      -1.027065      2.356988      1.807460

$Tuberculosis
Tuberculosis|(Intercept) Tuberculosis|Either
      -12.22120      10.21823

$LungCancer
LungCancer|(Intercept) LungCancer|Either
      -12.07565      14.18547

$Bronchitis
Bronchitis|(Intercept) Bronchitis|Dyspnea
      -1.388644      3.200393

$Either
Either|(Intercept) Either|XRay Either|Dyspnea
      -8.656348      8.259773      1.538789

$XRay
XRay|(Intercept)
      -2.052496

$Dyspnea
Dyspnea|(Intercept)
      -0.1201444
```

```
$Asia
Asia|intercept Tuberculosis
[1,]      -4.811371      1.766849

$Smoking
Smoking|intercept LungCancer Bronchitis
[1,]      -1.027075      2.357079      1.807472

$Tuberculosis
Tuberculosis|intercept Either
[1,]      -8.517393      6.516139

$LungCancer
LungCancer|intercept Either
[1,]      -8.517393      10.62598

$Bronchitis
Bronchitis|intercept Dyspnea
[1,]      -1.388655      3.200415

$Either
Either|intercept XRay Dyspnea
[1,]      -8.665128      8.268402      1.539146

$XRay
XRay|intercept
[1,]      -2.0525

$Dyspnea
Dyspnea|intercept
[1,]      -0.1201443
```

ASIA: KNOWN NETWORK

```
fitabn(dag.m = ~Asia|Tuberculosis+
  Tuberculosis|Either +
  Either|XRay:Dyspnea +
  Smoking|Bronchitis:LungCancer +
  LungCancer|Either +
  Bronchitis|Dyspnea,data.df = asia,data.dists = dist)$modes
```

```
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```

```
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      -2.052496

$Dyspnea
Dyspnea|(Intercept)
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```

```
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```